FIG/IAG/UN ICG/HKMO Technical Seminar Reference Frames in Practice -*Reference Frames, Kinematics and Dynamic Datums*



Kinematic Frames and Deformation Modelling



Istanbul, Turkey 4-5 May 2018 1





Semi-dynamic datums

Coordinates transformed to common reference epoch using deformation model cGNSS for active control

Plate fixed datums

- NAD83 Probably the best example
- Removes the need for modeling secular velocities
- Can be combined with a deformation model







Secular Velocity Field

- Red shows global model from Kreemer et al across New Zealand and part SP
- Over much of this area ectors derived from plate models (white) are adequate
- Not in plate boundary zones

Velocity grid from Kreemer et al 2014

Active faults: Malborourgh Fault



The Woodchester Wall



Left lateral and reverse of ~1.5-2m

Woodchester Station



















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INSAR



Hamling et al - 2017



SSE



If we model the SSEs (green line) we get a very different velocity than if we averaverage through them SPM ENU coordinate



Strain rate Field

- Maximum shear strain rates show the derivative of the velocity field
- High strain rates mean that if the NDM is not applied properly distortions will build
- These can effect users even if the baselines are short
- Particularly if the epoch date is a long time in the past

500 1000 1400 2500 100 1400 2500

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Conclusions

- Deformation models can are required to shift coordinates to reference epoch of datum
- Deformation models can have
 - Secular velocities
 - Post-seismic relaxation
- Needed to support time dependent least square adjustments and datum transformations for semi-



CP1 This would be a good segway into your talk Chris.I could put an explicate plug here if you want. Christopher Pearson; 15.08.2013