



LADS Technology

LADS - Laser Airborne Depth Sounder

- Hydrographic Survey / Shallow Water Mapping tool based on Lidar technology
- or "Airborne Lidar Bathymetry" (ALB) technology
- System mounted inside an aircraft
- Pulses of laser light are used to measure the depth of water and height of features (ie rocks, islands, beach gradients)
- Technology designed principally for Nautical Charting applications, ALB technology is used now in other applications such as:
 - Coastal Zone Management
 - Marine and Coastal Engineering
 - Pre-Seismic surveys for O&G Industry
 - Delineation of Baselines for EEZ/UNCLOS



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igro LADS Technical Philosophy
Applications
Nautical Charting
From the commencement of operations in 1992, the focus of the hardware and software has been to collect data for nautical charting. This requires:
 robust algorithms based on signal to noise ratio, to detect the seabed and small objects from noise
Coastal Zone Management and Habitat Mapping
Due to the continuous development process the Fugro LADS systems has developed from it roots of nautical charting to coastal zone management and habitat mapping applications. Development of capabilities for:
digital imagery
hyperspectral data
 seabed reflectivity and seabed classification
have enabled the Fugro LADS system to used for coastal zone management, habitat mapping and tsunami inundation modelling applications
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Fugro LADS Mk 3

Major Components

The Fugro LADS Mk 3 system has been redesigned as two main units:

- 1. an equipment cabinet, and
- 2. a sensor head unit

With ancillary units:

- 3. an operator's laptop, and
- 4. a pilot's display

The equipment cabinet weight 97 kg and the sensor head 135 kg The current draw is 70 Amps at 28Vdc, with an additional 35 Amps for the cooling unit.



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ro LADS M	k 3 - System Specifications
FEATURE	SPECIFICATION
Aircraft Type	Cessna 441
Survey Configuration	Altitude 1200 to 3000 feet, speed 125 to 175 knots.
Operational Capability	Full day or night operation, all weather (VFR, IFR)
Airborne Survey Crew	1 operator (plus observer optional)
Laser Rate	1.5 kHz
Depth Range	0 to 80 m (dependent on water clarity)
Topographic Range	to 50 m above sea level.
Sounding Density	Nominal patterns 2x2 m, 2.5x2.5m, 3x3 m, 4x4 m, 5x5 m and 6x5 m,
Swall Width	430 m at 6x5 m, 175 kts 360 m at 5x5 m, 175 kts 268 m at 4x4 m, 140kts 150 m at 3x3 m, 148 kts 150 m at 3x3 m, 148 kts 126 m at 2.5x2.5 m, 125 kts 79 m at 2x2 m, 122 kts
Scan Pattern	Rectilinear
Position Systems	WADGPS, DGPS and KGPS.
GPS Receiver/IMU	Applanix POS AV 610 V5 (embedded Trimble BD960 receiver L1, L2, Glonass, DGPS)
Horizontal Accuracy	IHO Order 1 (5 m + 5% of water depth at 95% confidence)
Vertical Accuracy	IHO Order 1 (refer to table 4.3 in following section)
Object Detection	2m cube (IHO Order 1a), dependant on water clarity, sounding density and depth.
Laser Power	Nominal 7 mJ Green, 5mJ beneath aircraft.
Digital Images	Redlake Mega plus II ES2020 high speed digital camera with ultra wide angle lens.
Digital Mosaic Imagery	Images collected at 1 Hz merged to mosaic with resolution nominally 40cm per pixel, accuracy 5m 95% CEP.
Relative Reflectivity	0 – 255 value for per pulse seabed reflectivity at 532nm. Values are relative and scaled across entire survey to maximise dynamic range.







