

Agenda

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- Introduction & Agenda
- Evolution of mobile liDAR data processing
 - Factors affecting liDAR Accuracy
 - Summary of Traditional workflow
- Processing of mobile liDAR data today
 - Planes, Tie Planes & adjustments
- Case Study Kelowna & Vernon, British Columbia
 - Urban & Rural scenarios
- Challenges using the technology moving forward
 - Collection Techniques
 - Processing Techniques
- Time for questions

Challenges Present in mobile LiDAR

Survey operations

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- Systematic errors
- How 'good' is 'good'?
 - Accuracy verification?
- Data misalignment
 - Internally
 - To control
- Correcting misalignments need effort to fix
 - DASHMap, Terramatch
- Rescan

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Proposed solution

Motivation: A rigorous methodology that provides thorough accuracy control, not just locally for control areas, but the entire project area.

- Free of blunders & systematic errors
- Accuracy calculated & reported
- Iterative
- Incremental

Requirements: Redundancy!

Lidar Mapping Suite (LMS) originally released for airborne lidar, now enhanced for mobile lidar also.



S1 Blue S2 Pink

Planes can be exported as ESRI shape files



Point to plane (ds) analysis - used for assessing quality of the point cloud data.



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Tie Plane Determination & Selection

- Determines correspondence between lines & selects appropriate tie planes for self calibration
 - Based upon the point to plane analysis
 - Selection criteria includes size, shape, no. points, slope, orientation fitting error
 - Redundancy!





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LMS Methodology – Self Calibration



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Requirement: Redundant information

Least squares observation equation

 $\mathbf{g}_{i,j} = n_{x,j} x_i + n_{y,j} y_i + n_{z,j} z_i = 0$

where

 $\mathbf{x}_i = f(obs., cal. par., corrections)$

 $obs. = l_r, \theta, x, y, z, r, p, h$

Least squares solution

Determine a set of corrections by minimizing the weighted square sum of the observation residuals

⇒ Applying the correction while reprocessing laser points

LMS Methodology – Self Calibration

- Sensor parameters
 - Optical calibration
- Boresight ————
 - Roll, pitch, heading
- Position
 - From POS
- Orientation
 - From POS

- Keep Fixed
- Free Unknown
- Constrain Unknown

- Per Mission
- Per Surveyed Line





Using Ground Control in LMS is <u>optional</u> but will improve data accuracy

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How should GCP's be collected?

On flat (planar) surfaces in multiple dimensions











- May 21 & May 23, 2013
- Kelowna & Vernon, British Columbia on Highway 97.



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Survey Time: 1h 53min Distance: 77.8 km Objective: To survey Highway 97 starting in Kelowna and ending north of Vernon, both directions.

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May 23, 2013 Collect

Survey Time: 1h 14min Distance: 46.9 km Objective: Complete Highway 97 between Vernon & Kelowna. Scan a major intersection within Vernon. Weather!

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- Rained on May 21, 22 & morning of 23rd
- Time constraints
- Multiple days of collection leading to misalignments between the two datasets.
 - Factors Affecting Accuracy!
 - How do we make these data sets align!?

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Urban Processing Environment





(i) Block status: Tie Plane Determina	tion don	e, Tie I	Plane S	election done	e, Determi	ne Self-Ca	libration I	Parameters do
Project Information	3) Ac	urad	cy Ver	rificatio	n - Ba:	sic		
Control Site Quality								
Accuracy Verification - Basic	(c)	At	all t	tie plane	s - una	correct	ed las	er points
Roof line analysis								
Control sites								
All tie planes	L	ne	Ch	#Points	Mean-o	RMS-d	Std-d	Ratio
Selected tie planes								
Self-Calibration Results	r00	01	S1	1212307	-0.00:	L 0.010	0.013	0.765
Adjustment Information	LOO	01	S 2	865055	0.00:	L 0.009	0.012	0.731
Parameter group assignments	r00	04	S1	140320	-0.053	0.057	0.012	4.762
Sensor corrections	LOC	04	S 2	78781	-0.030	0.046	0.014	3.309
Boresight corrections	LOO	05	S1	219169	-0.005	5 0.018	0.014	1.308
Position corrections	LO(05	s2	277167	0.000	0.018	0.012	1.461
Orientation corrections	LOO	06	S1	117576	-0.010	0.028	0.012	2.349
Accuracy Verification - Refined	r00	06	S 2	96494	-0.01	L 0.029	0.013	2.238
Roof line analysis	r00	07	S1	109389	-0.025	5 0.045	0.012	3.687
Control sites	LOO	07	S 2	99141	-0.01	0.036	0.013	2.753
All tie planes	F0(08	S1	108570	-0.023	L 0.039	0.012	3.334
Selected tie planes	F00	08	s 2	117904	-0.018	3 0.034	0.015	2.248
	F00	09	S1	130477	-0.01	7 0.043	0.013	3.348
	F 00	09	s 2	186353	-0.03	9 0.054	0.011	5.036
	F 00	10	S1	210885	-0.000	5 0.038	0.012	3.255
	L 00	10	s 2	246880	-0.004	1 0.042	0.013	3.316
	r00	11	S1	711630	-0.012	2 0.061	0.011	5.562
	T00	11	s 2	696413	-0.000	5 0.040	0.013	3.024
	T00	12	S1	497737	-0.009	9 0.041	0.011	3.624
	T00	12	s 2	588120	-0.000	5 0.038	0.013	2.932
	T00	13	S1	399234	-0.018	3 0.036	0.013	2.693
	т.О.(13	S 2	389194	-0.014	0.027	0.012	2.139
	L 00	14	S1	596672	-0.002	2 0.016	0.013	1.229
	F00	14	s 2	587738	-0.003	L 0.015	0.012	1.180
	100	10	51	102302	-0.00	0.021	0.011	1.001
	F00	15	s 2	227574	-0.003	8 0.020	0.012	1.716
	F00	16	S1	180510	-0.012	2 0.032	0.012	2.695
	TO(16	s 2	218214	-0.004	1 0.017	0.013	1.326
	F00	17	S1	127206	-0.000	5 0.022	0.012	1.906
	F00	17	s 2	172173	-0.003	5 0.021	0.012	1.780

L014 - S1 - **596,627** L014 - S2 - **587,738**

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Tie Plane Determination & Selection

 Block status: Tie Plane Determina 	ation dor	e, Tie F	'lane Sel	ection done	e, Determin	ie Self-Ca	libration F	Parameter
Project Information	(3) Ac	curac	y Ver	ificatio	n - Bas	ic		
Control Site Quality								
Accuracy Verification - Basic	(d	At	selec	ted tie	planes ·	- unco	rrected	laser
Roof line analysis								
Control sites								
All tie planes	L	ine	Ch	#Points	Mean-d	RMS-d	Std-d	Ratio
Selected tie planes								
Self-Calibration Results	r0	001	S1	671296	-0.001	0.011	0.013	0.847
Adjustment Information	r0	001	S 2	389044	0.001	0.010	0.011	0.907
Parameter group assignments	r0	004	S1	124859	-0.055	0.059	0.012	4.824
Sensor corrections	r0	004	S 2	42114	-0.037	0.053	0.013	3.970
Boresight corrections	r0	005	S1	29242	-0.015	0.027	0.012	2.246
Position corrections	r0	005	S 2	28098	-0.006	0.018	0.012	1.507
Orientation corrections	r0	006	31	62656	-0.011	0.026	0.011	2.271
Accuracy Verification - Refined	r0	006	32	51874	-0.013	0.027	0.014	1.973
Roof line analysis	r0	007	31	63224	-0.028	0.047	0.012	4.004
Control sites	r0	007	32	65312	-0.014	0.032	0.014	2.327
All tie planes	P0	008	S1	62014	-0.017	0.034	0.012	2.972
Selected tie planes	P0	008	S2	69805	-0.014	0.028	0.015	1.873
	LO	109	S1	83734	-0.016	0.036	0.013	2.815
	LO	109	S 2	117549	-0.030	0.045	0.011	3.898
	ΓO	010	S1	137724	-0.012	0.029	0.012	2.434
	LO	010	S 2	146311	-0.004	0.023	0.013	1.824
	P0	011	S1	391266	-0.022	0.051	0.011	4.592
	LO	011	S 2	402733	-0.006	0.034	0.013	2.619
	LO	112	S1	282049	-0.018	0.051	0.011	4.526
	FO	012	S 2	341056	-0.006	0.034	0.012	2.784
	LO	313	S1	88002	-0.002	0.021	0.012	1.772
	T.0	113	82	68177	-0.008	0.021	0.012	1.849
	LU	J14	S1	512345	-0.002	0.015	0.013	1.091
	P0	J14	92	465163	0.002	0.009	0.012	0.728
	20	115	20	100331	-0.005	0.022	0.011	1.334
	- U	112	82	T09/68	0.000	0.013	0.012	1.125
	10	110	81 81	11/2002	-0.003	0.021	0.012	1.047
	T0	112	3Z 91	L162U2	-0.001	0.013	0.013	2 021
	10	117	31 a2	07402	-0.008	0.023	0.012	1 000
	70	111	32	2/403	-0.001	0.012	0.012	1.000

L014 - S1 - **512,345** L014 - S2 - **465,163**

- S1 85% of tie planes determined were selected
- S2 79% of tie planes determined were selected



Self Calibration Results



-0.12

-150

-100

-50

150

100

-100 0 50 Optical scan angle [deg] © Сорунуна 2013, Ора IQI.

-50

-150

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and

stan

AVP -0.12

Accuracy Height Report

0 50 Optical scan angle (deg)

150

100





Use of GCP's in processing

TypeSlope [deg] #Points Min-d Mean-d Max-d RMS-d Horizontal 0 - 5Mean distance = 0.032n RMS = 0.044mNertical 85 - 900Iotal119 0.001 0.032 0.145 0.044Accuracy Verification - Refined(b) At control sites - corrected laser points compared to control info (without blunders)TypeSlope [deg] #Points Min-d Mean-d Max-d RMS-d Horizontal 0 - 5Morizontal 0 - 5111 0.000 0.014 0.091 0.021Wettical 85 - 900Vertical 85 - 900TypeSlope [deg] #Points Min-d Mean-d Max-d RMS-d Horizontal 0 - 5Morizontal 0 - 5111 0.000 0.014 0.091 0.021Wettical 85 - 900Vertical 85 - 900Total111 0.000 0.014 0.091 0.021Control sites - BlundersMean distance = 0.014n RMS = 0.021mControl sites - Blunders0.116 control Kalowna 254Control sites - Blunders0.116 control Kalowna 675Control Relewna 6740.086 control Relewna 677Control Relewna 6770.086 control Relewna 677	(b) At control site	s - uncorrected laser points comp	red to control info
Horizontal 0 - 5 119 0.001 0.032 0.145 0.044 Sloped 5 - 85 0 Vertical 85 - 90 0 Potal 119 0.001 0.032 0.145 0.044 (b) At control sites - corrected laser points compared to control info (without blunders) Type Slope [deg] #Points Min-d Mean-d Max-d RMS-d Horizontal 0 - 5 111 0.000 0.014 0.091 0.021 Horizontal 0 - 5 111 0.000 0.014 0.091 0.021 Total 111 0.000 0.014 0.091 0.021 Control sites - Elunders Control sites - Elunders Control Kelowna 254 0.116 control Kelowna 254 0.116 control Kelowna 257 0.095 control Kelowna 673 0.095 control Kelowna 677 0.096	Type Slope [d	eg] #Points Min-d Mean-d Max-d RM:	Maan diatanaa 0.022m
Intervent Verification - Refined (b) At control sites - corrected laser points compared to control info (without blunders) Type Slope [deg] #Points Min-d Mean-d Max-d FMB-d Horizontal 0 - 5 111 0.000 0.014 0.091 0.021 Sloped 5 - 85 0 Vertical 85 - 90 0 Total 111 0.000 0.014 0.091 0.021 Control sites - Blunders Mean distance = 0.014m Control sites - Blunders MMS = 0.021m Control Site Point ID Separation MMS = 0.021m control_Kelowna 254 0.116 control_Kelowna 774 0.040 control_Kelowna 675 0.095 control_Kelowna 677 0.095 control_Kelowna 677 0.096	Horizontal 0 - 5 Sloped 5 - 85 Vertical 85 - 90	119 0.001 0.032 0.145 0.0 0 0	RMS = 0.044m
Accuracy Verification - Refined (b) At control sites - corrected laser points compared to control info (without blunders) 	Fotal	119 0.001 0.032 0.145 0.0	144
Total 111 0.000 0.014 0.091 0.021 RMS = 0.021m Control sites - Blunders	Horizontal 0 - 5 Sloped 5 - 85 Vertical 85 - 90	111 0.000 0.014 0.091 0.021 0 0	Mean distance = 0.014m
Control sites - Blunders Control Site Point ID Separation control_Kelowna 254 0.116 control_Kelowna 928 0.116 control_Kelowna 920 0.040 control_Kelowna 874 0.040 control_Kelowna 675 0.095 control_Kelowna 675 0.095 control_Kelowna 677 0.096 control_Kelowna 1004 0.096	Total	111 0.000 0.014 0.091 0.021	RMS = 0.021m
control_Kelowna 254 0.116 control_Kelowna 928 0.116 control_Kelowna 200 0.040 control_Kelowna 874 0.040 control_Kelowna 675 0.095 control_Kelowna 677 0.096 control_Kelowna 1000 0.096			-
Control_Nelowna 234 0.116 control_Kelowna 928 0.116 control_Kelowna 200 0.040 control_Kelowna 874 0.040 control_Kelowna 675 0.095 control_Kelowna 677 0.096 control_Kelowna 1000 0.096	Control sites - Blunder: Control Site Point T	5) Separation	
control_Kelowna 200 0.040 control_Kelowna 874 0.040 control_Kelowna 675 0.095 control_Kelowna 1004 0.095 control_Kelowna 677 0.096	Control sites - Blunder	s) Separation 	
control_Kelowna 874 0.040 control Kelowna 675 0.095 control_Kelowna 1004 0.095 control_Kelowna 677 0.096 control_Kelowna 1000 0.096	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 928	s) Separation 	
control_Kelowna 675 0.095 control_Kelowna 1004 0.095 control_Kelowna 677 0.096 control_Kelowna 1000 0.096	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 208 control_Kelowna 200	s Separation 0.116 0.016 0.040	
control_Kelowna 1004 0.095 control_Kelowna 677 0.096 control_Kelowna 1000 0.096	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 928 control_Kelowna 200 control_Kelowna 874	s Separation 0.116 0.116 0.040 0.040	
control_Kelowna 677 0.096 control_Kelowna 1000 0.096	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 928 control_Kelowna 200 control_Kelowna 675	s 3eparation 0.116 0.116 0.040 0.040 0.095	
control_Kelowna 1000 0.096	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 200 control_Kelowna 874 control_Kelowna 675 control_Kelowna 1004	s Separation 0.116 0.116 0.040 0.040 0.095 0.095	
	Control sites - Blunder Control Site Point II control_Kelowna 254 control_Kelowna 200 control_Kelowna 874 control_Kelowna 675 control_Kelowna 677	<pre>> Separation 0.116 0.116 0.040 0.040 0.095 0.095 0.095 0.096</pre>	



Rural Processing Environment



May 21May 23



Rural Processing Environment



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Tie Plane Determination & Selection

 Block status: Tie Plane Determin 	nation done, Tie Plane Selection done, Determine Self-Calibration Parameters done, Retrieve Self-Calibration Parameters done	
Project Information	(3) Accuracy Verification - Basic	
Control Site Quality		
Accuracy Verification - Basic	(c) At all tie planes - uncorrected laser points compared to uncorrected planes	
Roof line analysis		
Control sites		
All tie planes	Line Ch #Points Mean-d RMS-d Std-d Ratio	
Selected tie planes		
Self-Calibration Results	L0001 S1 1311713 -0.002 0.008 0.012 0.671	
Adjustment Information	L0001 S2 1272061 0.002 0.008 0.010 0.804	
Parameter group assignments	10002 s1 1738375 -0.002 0.008 0.011 0.677	
Sensor corrections	L0002 S2 1604429 0.002 0.011 0.010 1.063	
Boresight corrections	L0003 S1 342065 -0.001 0.009 0.012 0.764	
Position corrections	10003 s2 310638 0.004 0.017 0.010 1.739	
Orientation corrections	L0004 S1 12779 0.002 0.015 0.010 1.452	
Accuracy Verification - Refined	L0004 S2 9041 -0.003 0.016 0.014 1.120	
Roof line analysis	10005 S1 35641 -0.007 0.016 0.011 1.401	
Control sites	L0005 S2 28712 -0.009 0.022 0.011 2.022	
All tie planes	L0006 S1 112127 0.002 0.016 0.011 1.415	
Selected tie planes	L0006 S2 160762 0.001 0.014 0.012 1.160	
	L0007 S1 179603 0.003 0.016 0.012 1.281	
	<u>10007 82 98125 0.003 0.015 0.011 1.42</u> 7	
	L0008 S1 257243 0.002 0.018 0.013 1.4 3	
	L0008 S2 137992 0.005 0.018 0.009 1.9 3	
	10009 51 440330 -0.002 0.015 0.012 1.246	
	L0009 S2 410643 0.001 0.010 0.010 1.036	
	L0010 S1 571767 -0.002 0.010 0.012 0.850	
	10010 82 609829 0.003 0.009 0.010 0.925	
	L0011 S1 419514 -0.002 0.011 0.012 0.879	
	L0011 S2 317571 0.001 0.012 0.011 1.111	
	L0012 S1 631601 -0.001 0.011 0.012 0.960	
	L0012 S2 622333 0.001 0.013 0.010 1.274	
	L0013 S1 1128983 -0.001 0.008 0.011 0.700	
	L0013 S2 980177 0.001 0.010 0.010 1.078	
	L0014 S1 337470 0.001 0.011 0.012 0.942	
	L0014 S2 232058 -0.001 0.011 0.009 1.233	
	L0015 S1 197436 -0.001 0.014 0.011 1.334	
	L0015 S2 151501 0.003 0.012 0.011 1.015	
	L0016 31 853209 -0.001 0.009 0.011 0.804	
	L0016 32 778886 0.002 0.009 0.011 0.806	
	L0017 S1 132103 0.002 0.018 0.011 1.560	
	L0017 32 103403 0.004 0.017 0.012 1.465	
	L0018 S1 511257 -0.000 0.012 0.012 1.005	
	L0018 S2 248691 0.003 0.011 0.010 1.074	
	L0019 S1 233186 -0.002 0.014 0.012 1.201	
	L0019 S2 216457 0.000 0.014 0.011 1.281	
	L0020 S1 620816 -0.002 0.008 0.011 0.743	
1	L T0000 02 E01142 0 002 0 012 0 010 1 114	

L008 - S1 - **257,243** L008 - S2 - **137,992**

Project Information	(3) Accurac	cy Ver	rification - Basic	1
Control Site Quality				1000 01 02 466
Accuracy Verification - Basic	(d) At	seled	cted tie planes - uncorrected laser points compared to uncorrected planes	L000 - 3 - 93,400
Roof line analysis				
Control sites				1 1008 - S2 - 45 346
All tie planes	Line	Ch	#Points Mean-d RMS-d Std-d Ratio	
Selected the planes			707010 0 000 0 000 0 010 0 700	
self-Calibration Results	10001	31		
Adjustment information	10001	32		
Sensor corrections	10002	82	527149 0 002 0 012 0 010 1 244	
Boresight corrections	10002	91	122405 0 001 0 002 0 012 0 704	
Position corrections	T-0003	82		
Orientation corrections	10004	S1	9473 0.003 0.011 0.010 1.128	151 - 36% of planes
ccuracy Verification - Refined	10004	32	7068 -0.005 0.014 0.015 0.923	
Roof line analysis	L0005	31	26743 -0.007 0.016 0.011 1.439	
Control sites	L0005	\$2	19092 -0.012 0.025 0.012 2.089	ovtracted wore
All tie planes	F0008	S1	86447 -0.001 0.013 0.011 1.198	
Selected tie planes	T0006	S 2	139591 0.001 0.013 0.012 1.071	
	10007	31	119534 0.003 0.015 0.012 1.212	coloctod
	F(00 /	54	01010 0.000 0.017 0.011 1.3/7	Selected
	P0008	S1	93466 0.006 0.026 0.013 2.035	
	F0008	\$2	45346 0.012 0.028 0.009 3.167	
	F000A	31	248836 -0.001 0.018 0.012 1.528	1 $(2) = 22%$ of plane
	T0008	\$2	201651 0.001 0.012 0.010 1.239	$\int JZ = JZ / 0$ UI plattes
	10010	31	345067 -0.002 0.011 0.011 0.926	
	10010	32	456135 0.002 0.009 0.010 0.937	autra at a d una ra
	10011	31	354451 -0.002 0.011 0.012 0.908	extracted were
	10011	52		
	10012	81 82	595055 -0.001 0.012 0.012 0.928	
	1.0012	91 91		l selected
	T-0013	82	931542 0.001 0.010 0.010 1.080	
	T-0014	31	287893 0.001 0.011 0.012 0.982	
	L0014	s2	200980 -0.002 0.011 0.009 1.209	
	L0015	s1	98878 -0.001 0.017 0.010 1.667	1
	T-0015	92	47380 0 005 0 015 0 014 1 122	1

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Accuracy Height Report



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Challenges moving forward

- Vertical plane availability & orientation
 - POS Accuracy
- Collection techniques
 - GCP's on planes (~ centre)
- Processing techniques
 - GCP's post collection, after planar extraction