

From the wisdom of the ages
to the challenges of modern world

FIG WORKING WEEK 2015

17–21 MAY SOFIA BULGARIA

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FIG Working Week
17 - 21 May, Bulgaria
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FIG SOFIA 2015

EVALUATING THE PERFORMANCE OF
KINEMATIC PPP AND DIFFERENTIAL KINEMATIC
METHODS IN RURAL AND URBAN AREAS

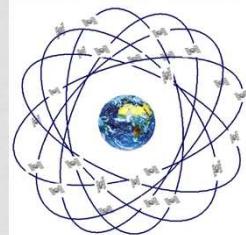
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SELÇUK ÜNİVERSİTESİ

Introduction: PPP

Precise Point Positioning (PPP) is a special case of zero difference processing and viable alternative to differential technique. PPP is cost effective since the point positioning is performed using a single GNSS receiver (at the user's position) and it is not require accessing to the observations of reference station with known coordinates.



Introduction: Web-Based Apps

Over the last few years several PPP software packages have been developed. PPP post processing services such as CSRS-PPP, MagicGNSS, GAPS, APPS provide converged float solutions at the centimeter level in static mode and at the decimeter level of accuracy in kinematic mode depending on observation duration .



CSRS-PPP

CSRS use both phase and code observations and has an option for users to select data in results including NAD83 and ITRF 2008.

Processing mode	
<input checked="" type="radio"/> Static	<input type="radio"/> Kinematic
NAD83	ITRF

In this study, performance of the kinematic PPP and Differential Kinematic methods were compared in three different routes including rural and urban regions. For the kinematic PPP process NRCan's CSRS-PPP online service and for the post process kinematic PPP application Leica Geo Office commercial software was used.

Experimental Work :Route-1

In order to compare kinematic PPP and differential kinematic methods three routes have different topographical conditions and satellite visibilities were selected. They are Campus- Ardicli Village, Campus and Bosna-Hersek District routes. Campus-Ardicli Village is in the plain rural area and there aren't any buildings or forest near the route that could be interfered with GNSS signal. It is 8.9 km long.



Experimental Work :Route-2

The Campus is the shortest route (3.8 km) including few high buildings that may possibly block the signals path.



Experimental Work :Route-3

Bosna-Hersek District is the longest route that has a lot of high buildings which may cause signal loss and decrease in the number of visible satellites. This route is 13.7 km long.



Experimental Work

In order to estimate differential kinematic coordinates, a reference station was located inside the campus area. In addition a receiver, placed on the vehicle, used as a rover.



Experimental Work

GPS data was collected at 1 second intervals with a maximum vehicle speed of 30 km/h and 10 degree cut off angle. Unlike other routes in order to investigate consistency of the results campus route was made 7 laps. The data obtained from the routes was prepared to use in the processes. The total number of observation data obtained for each route are 2100, 4700 and 2200 for Campus-Ardicli, Campus and Bosna-Hersek District respectively.

Experimental Work

In order to eliminate datum difference between differential kinematic and kinematic PPP applications, observation data of the reference station was processed by the static module of the CSRS-PPP software and estimated coordinates was used as a fixed coordinates of reference station for differential kinematic applications. Using Leica Geo Office 5.0 Software for differential kinematic processes, differential kinematic coordinates of the rover according to the reference station was estimated for three different routes. However some meaningless coordinates corresponding to Bosna-Hersek District route was determined because of signal loss and multipath.

Experimental WORK

Besides differential kinematic applications, kinematic PPP processes were made using kinematic module of CSRS-PPP software. While doing this, only observation files corresponding to each route were uploaded to the system and process results were received by e mail. Unlike the differential results, there was no meaningless results was found in the estimated coordinate files. After eliminating outlier coordinates of the differential results, their corresponding parts in the kinematic PPP results were also extracted for the comparison.

Experimental Work

Coordinate results estimated by two methods for the Campus-Ardicli route, which is in the rural area, are highly consistent in all directions.

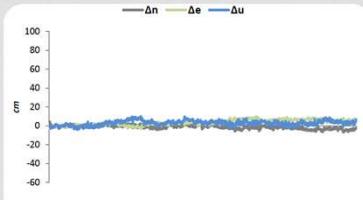


Figure 5 Coordinate Differences of Campus-Ardicli Village Route

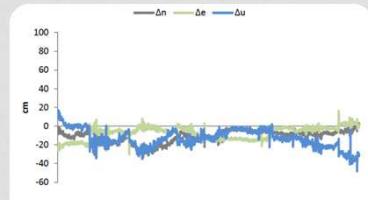


Figure 6 Coordinate Differences of Campus Route

Maximum difference can reach 40 cm level in up components for Campus-Route which includes 7 laps. Coordinate differences are similar for each laps.

Experimental Work

However when the Bosna-Hersek results were examined it can be seen in graph that differences are very high for all coordinate components. In addition there are meaningless leaps in the figure. These are associated with the differential kinematic coordinates.

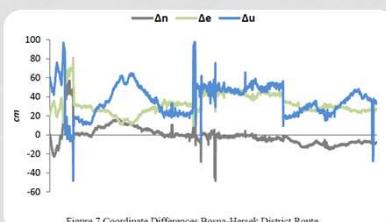
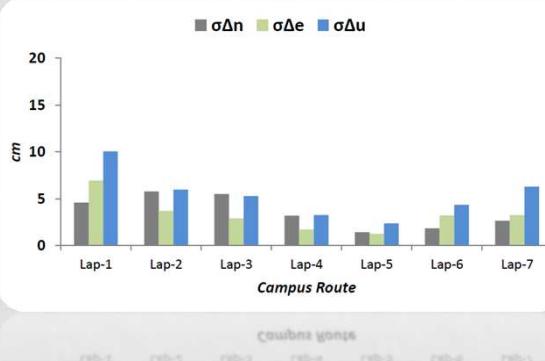


Figure 7 Coordinate Differences Bosna-Hersek District Route

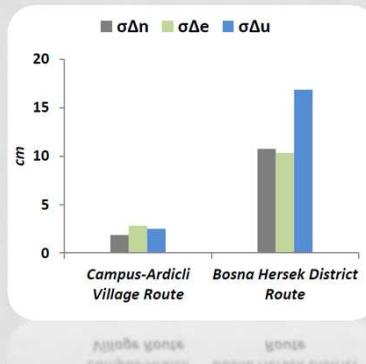
Standart Deviations

Besides coordinate differences, standard deviations of the coordinate components were also examined. Standard deviations of Campus route for 7 laps are similar in general. However they are a little larger in the first lap reaching 10 cm for up component. Standard deviations are 5 cm level in general. In addition standard deviations corresponding to 7 laps are 6.6 cm, 6.7 cm and 9.4 cm for north, east and up directions respectively.



Standart Deviations

As expected standard deviations corresponding to Campus-Ardicli route, in the rural area, are lower then the other routes, reaching maximum 3 cm level. However standard deviations of the coordinate differences related to the Bosna-Hersek District route are very high, particularly in the up directions.



Conclusion

According to the results, it is observed that kinematic PPP is a valuable method that can obtain precise coordinates for different satellite visibility condition. While using differential kinematic method the precise coordinates were obtained in rural area however some meaningless and less precise coordinates were estimated in urban areas. Coordinate differences are generally larger in the up components for the routes in the urban areas. In addition differences in all directions are clearer in Bosna-Hersek District Route which has many high buildings. Similar to the coordinate differences, standard deviations corresponding to the Bosna Hersek District Route have higher values.

END OF PRESENTATION

THANK YOU