

# Introduction to 3D Reference Frames

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#### Introduction

- ITRS
- ITRF
- Observing techniques of space geodesy
- Regional reference frames
- Local reference frames



## International Terrestrial Reference System (ITRS)

- An internationally-agreed set of prescriptions and conventions to define a Conventional Terrestrial Reference System
- Realised through creating a reference frame ITRF
- Connected to International Celestial Reference System (ICRS) via Earth Orientation Parameters (EOP)



## International Terrestrial Reference System (ITRS)

- An ITRS meets the following conditions:
  - Geocentric (origin is Earth centre of mass)
  - Uses the metre as the unit of length
  - Initial orientation given by BIH orientation at 1984
  - The time evolution of the orientation is ensured by using a no-net-rotation condition with regards to horizontal tectonic motions over the whole earth.
- The ITRS is of very little use to the practitioner
  - we need a realisation (some coordinates)



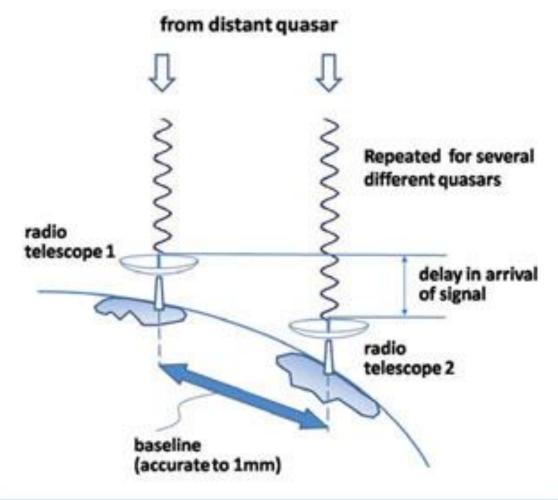
## International Terrestrial Reference Frame (ITRF)

- Follows the conventions set out for the ITRS
- Is re-realised every few years (ITRF89, ITRF90, ITRF91, ITRF92, ITRF93, ITRF94, ITRF95, ITRF96, ITRF97, ITRF2000, ITRF2005, ITRF2008, ITRF2014)
- Provides a set of coordinates and velocities for several hundred stations worldwide
- Uses a geocentric coordinate system (XYZ)
- Data from four space geodesy observing systems
- Most recent is ITRF2014





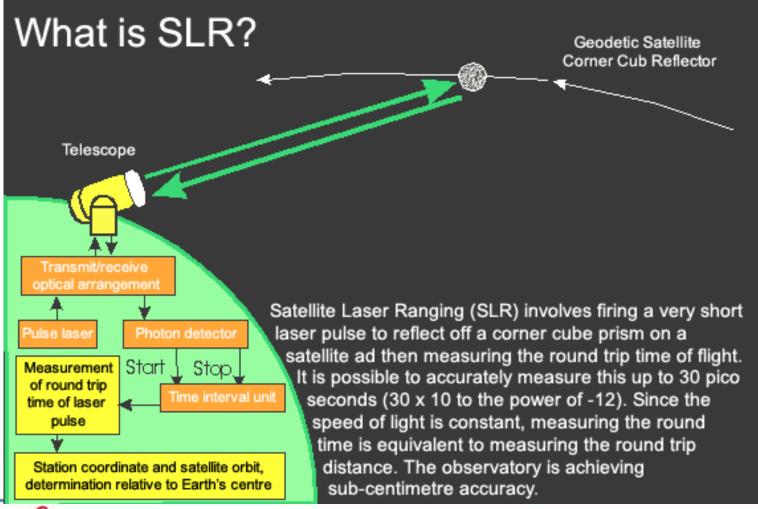
## **Very Long Baseline Interferometry (VLBI)**







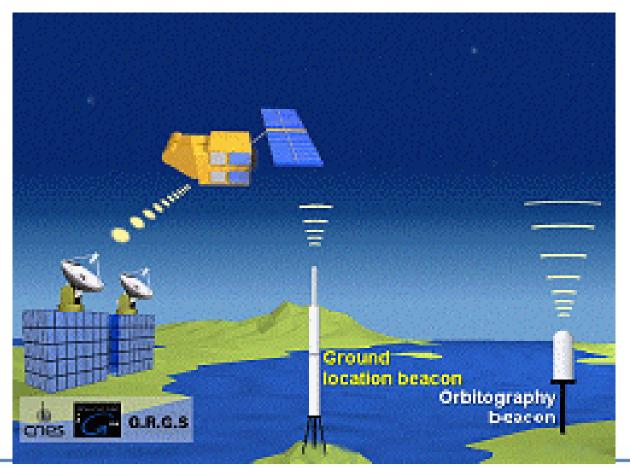
## **Satellite Laser Ranging (SLR)**



**BELS+ Training** 



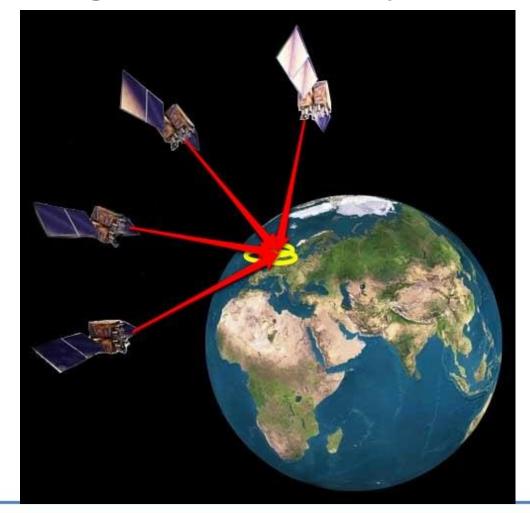
## **Doppler Orbitography and Radiopositioning** Integrated by Satellite (DORIS)







## Global Navigation Satellite Systems (GNSS)





## Global Navigation Satellite Systems (GNSS)

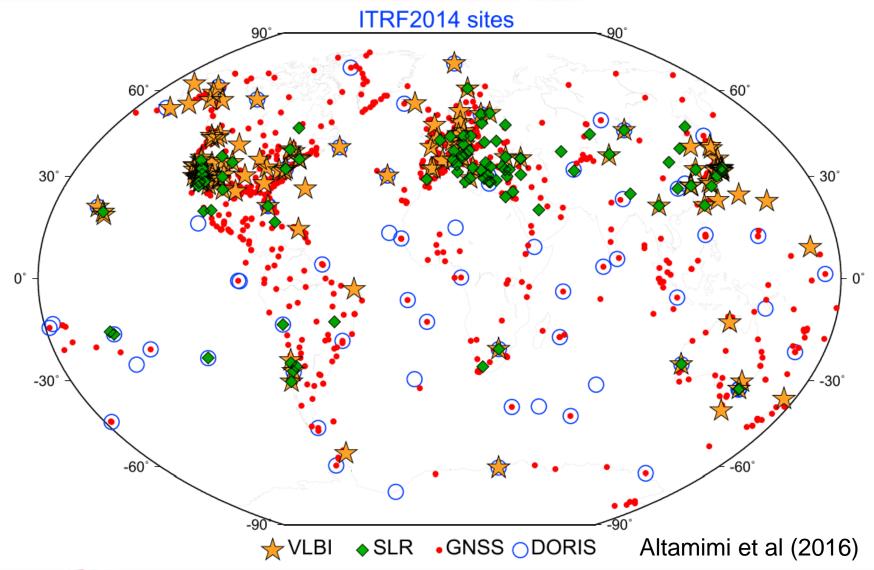




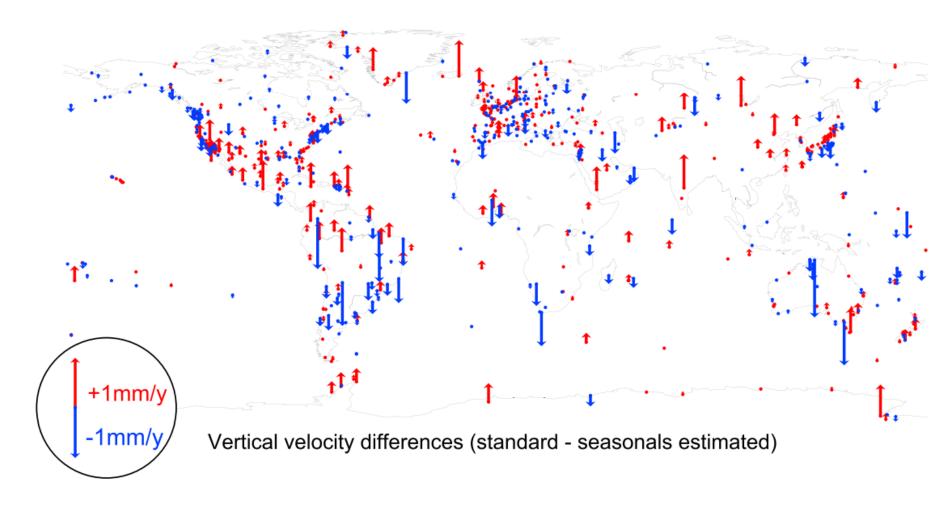
#### **ITRF2014**

- Based on all 4 space geodesy techniques
- Observations from 1980.0 to 2015.1 (but only a few stations have observations over the entire period)
- Accounts for annual and semi-annual signals
- Includes post-seismic deformation models for sites affected by significant earthquakes
- Products include coordinates, velocities and transformation parameters







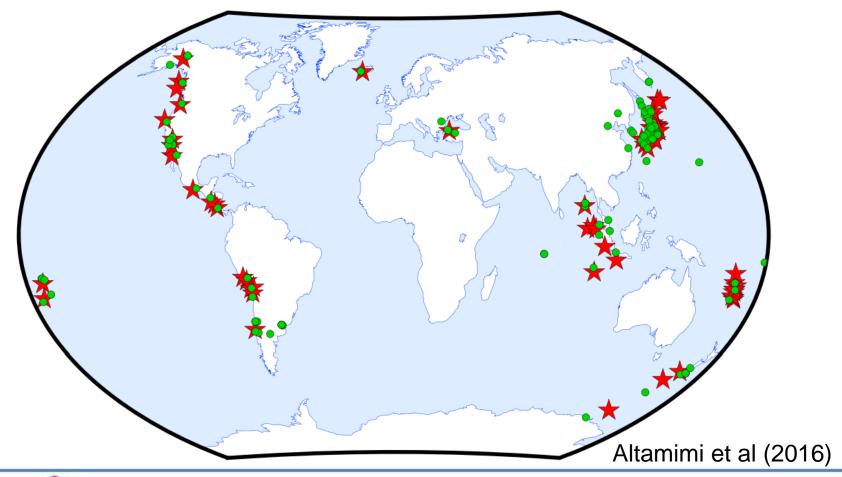


Altamimi et al (2016)



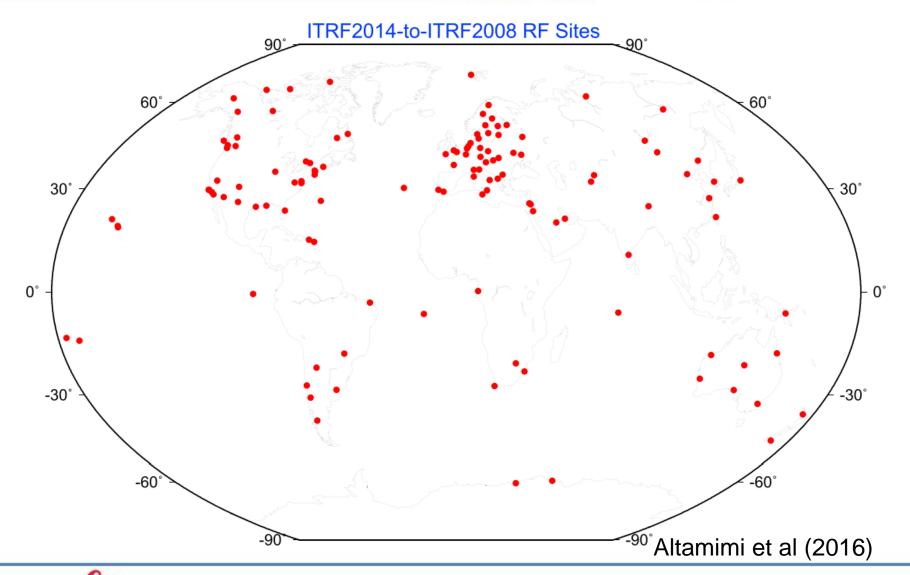


## Post-seismic Deformation Sites











#### **ITRF2014 to ITRF2008**

Altamimi et al (2016)

$$\begin{cases} \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i08} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i14} + T + D \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i14} + R \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i14} \\ \begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{pmatrix}_{i08} = \begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{pmatrix}_{i14} + \dot{T} + \dot{D} \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i14} + \dot{R} \begin{pmatrix} x \\ y \\ z \end{pmatrix}_{i14} \end{cases}$$

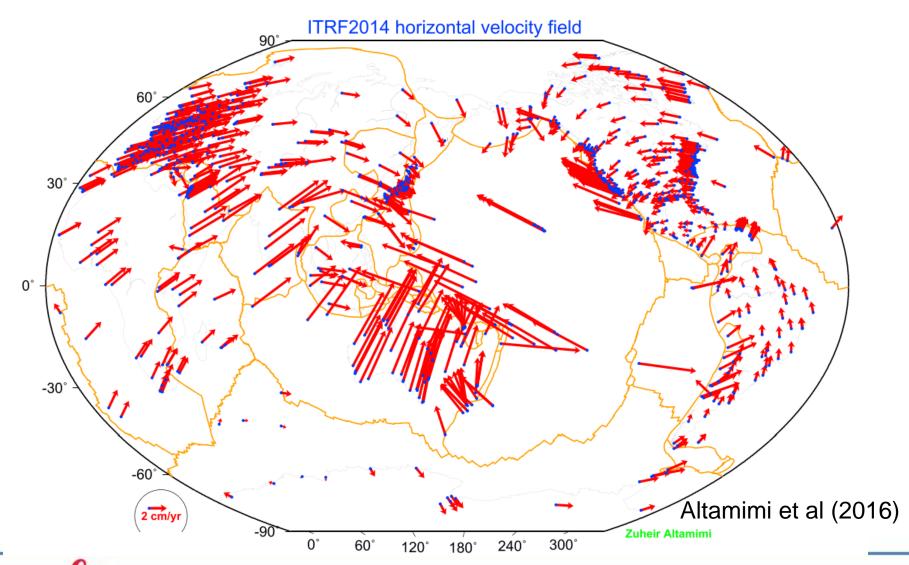
$$(4)$$

**Table 4.** Transformation Parameters at Epoch 2010.0 and Their Rates From ITRF2014 to ITRF2008, to Be Used With Equation (4)

	$T_x$ (mm)	$T_y$ (mm)	$T_z$ (mm)	D (ppb)	$R_{\chi}$ (mas)	$R_y$ (mas)	$R_z$ (mas)
	$\dot{T}_{x}$ (mm/yr)	$\dot{T}_y$ (mm/yr)	$\dot{T}_z$ (mm/yr)	Ď (ppb/yr)	$\dot{R}_{\chi}$ (mas/yr)	$\dot{R}_y$ (mas/yr)	$\dot{R}_z$ (mas/yr)
	1.6	1.9	2.4	-0.02	0.00	0.00	0.00
±	0.2	0.1	0.1	0.02	0.06	0.06	0.06
	0.0	0.0	-0.1	0.03	0.00	0.00	0.00
<u>+</u>	0.2	0.1	0.1	0.02	0.06	0.06	0.06

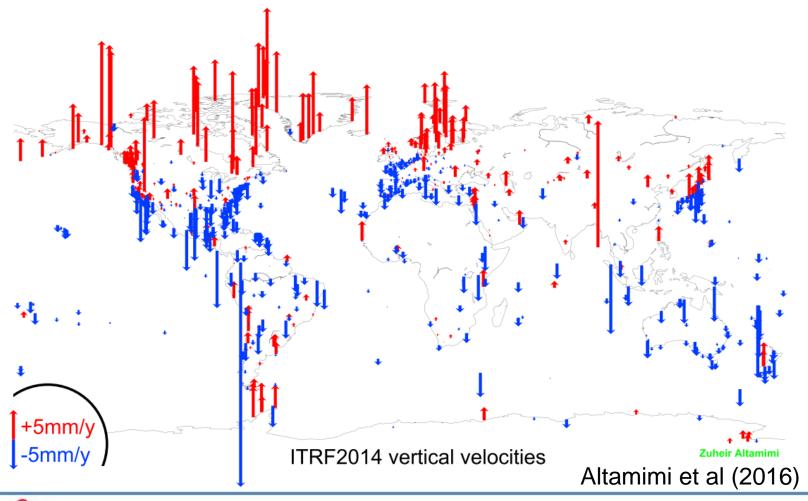
Sponsors: Leica Geosystems









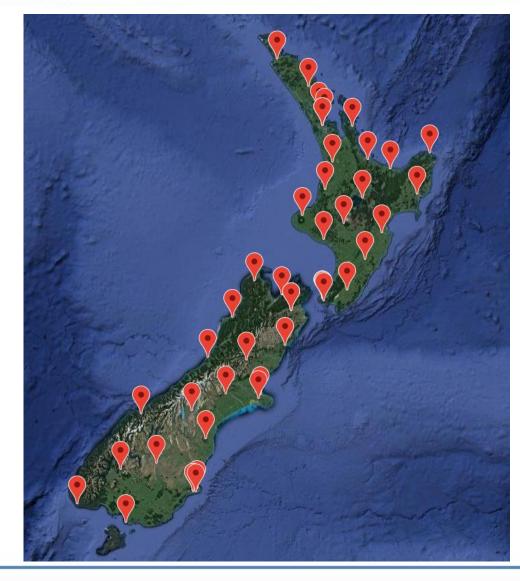


## **Regional Reference Frames**

- Cover large regions of the globe
- Greater densification of stations
- Easier (but slightly indirect) link to the ITRF
- Consists solely of GNSS stations (including ITRF GNSS stations)
- Coordinates, velocities and time series plots produced
- Africa AFREF
- Asia-Pacific APREF
- Europe EUREF
- North and South America SIRGAS

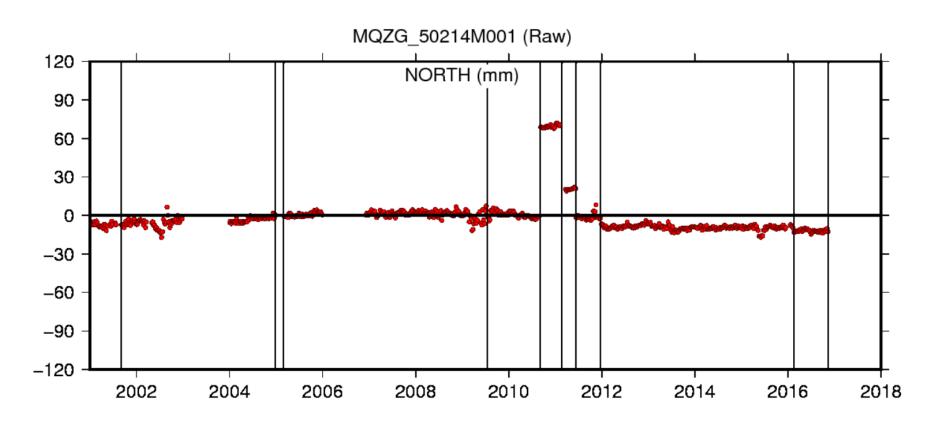


## **APREF Example**





## **APREF Example: Time Series**







#### **Local Reference Frames**

- Aim is to provide accurate spatial references
- Typically cover an entire country
- Traditionally defined using astronomy
- Modern frames defined through alignment to one of the ITRFs
- Reference Frame vs Datum
- Static vs dynamic/kinematic
- Semi-dynamic





#### Reference

### Open access journal article:

Altamimi, Z., P. Rebischung, L. Métivier, and X. Collilieux (2016), ITRF2014: A new release of the International Terrestrial Reference Frame modeling nonlinear station motions, *J. Geophys. Res. Solid Earth*, 121, 6109–6131, doi: 10.1002/2016JB013098.

