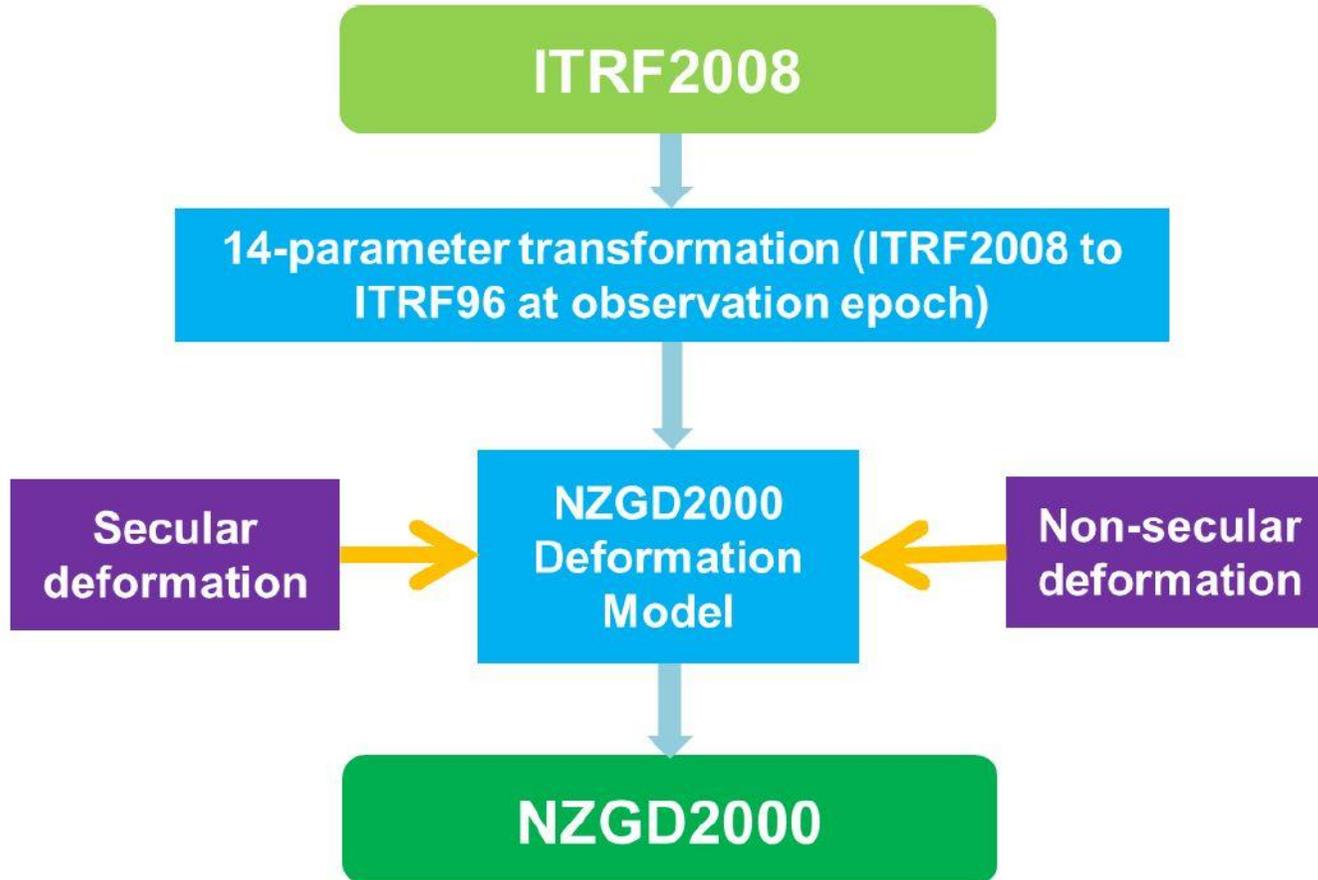




# Case study: the Kaikoura 2016 earthquake in New Zealand

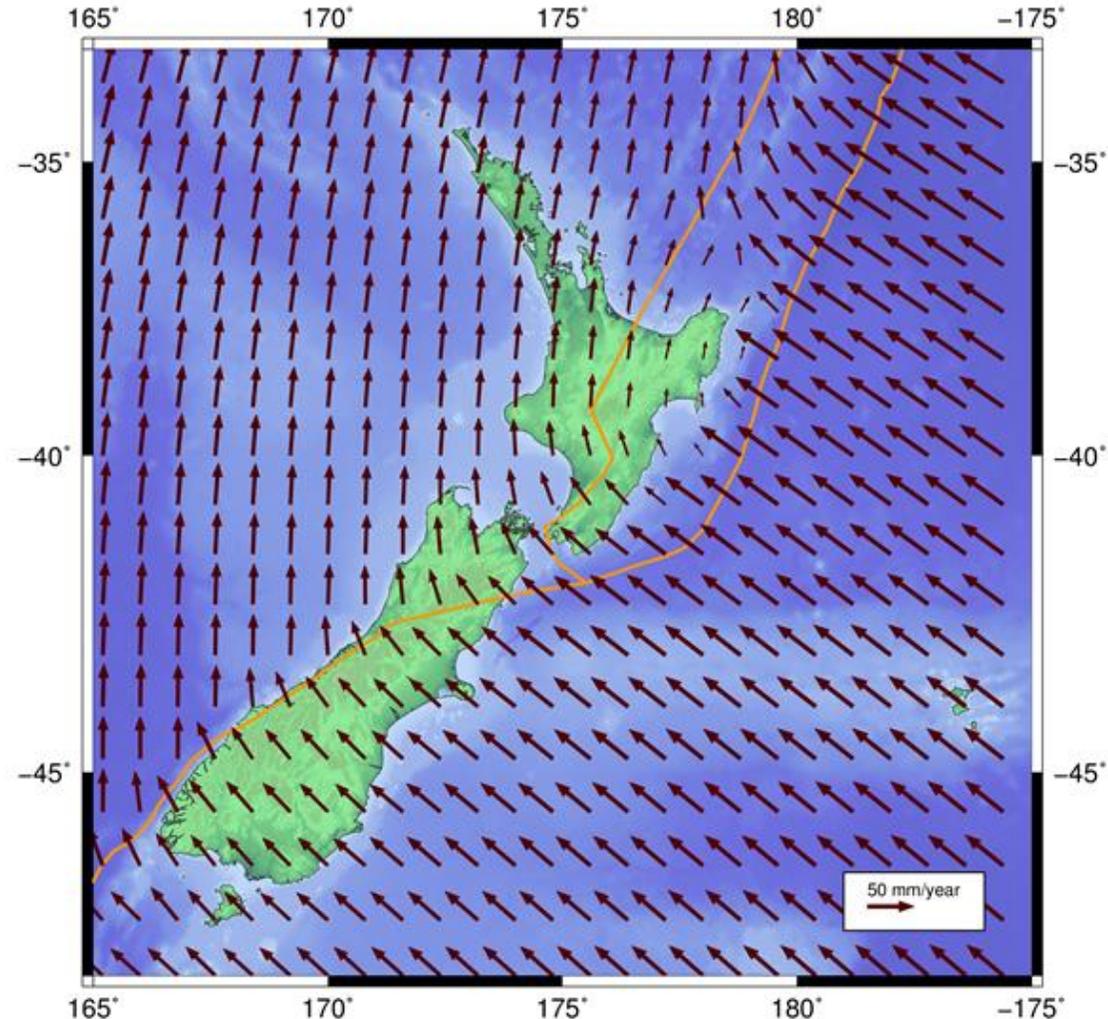
Chris Crook: Land Information New Zealand

Nic Donnelly: Land Information New Zealand



# NZGD2000 – deformation model

- Coordinates are fixed, except after an earthquake
- Deformation model manages tectonic movements
- New versions of deformation model published after earthquakes or when new data is available



Version	Reason
20000101	National deformation model - initial version
20130801	Update of national deformation model and patches for: Reverse patches for the following events: Dusky Sound, 2009 Darfield (Christchurch), September 2010 Christchurch, February 2011 Christchurch, June 2011 Christchurch, December 2011 + 3 other earthquakes
20140201	Patches for events: Cook Strait, 17 July 2013 Lake Grassmere, 16 August 2013
20160701	Reverse patches Christchurch, 14 February 2016
20170601	<i>Hybrid patch for Kaikoura 14 November 2016</i>

# The 2016 M7.8 Kaikoura eq

- Magnitude 7.8, 14 November 2016
- Multiple faults ruptured
- Displacements exceeding 5m (horizontal and vertical)
- Serious property and infrastructure damage
- Infrastructure includes spatial reference system (datum)



# Social setting



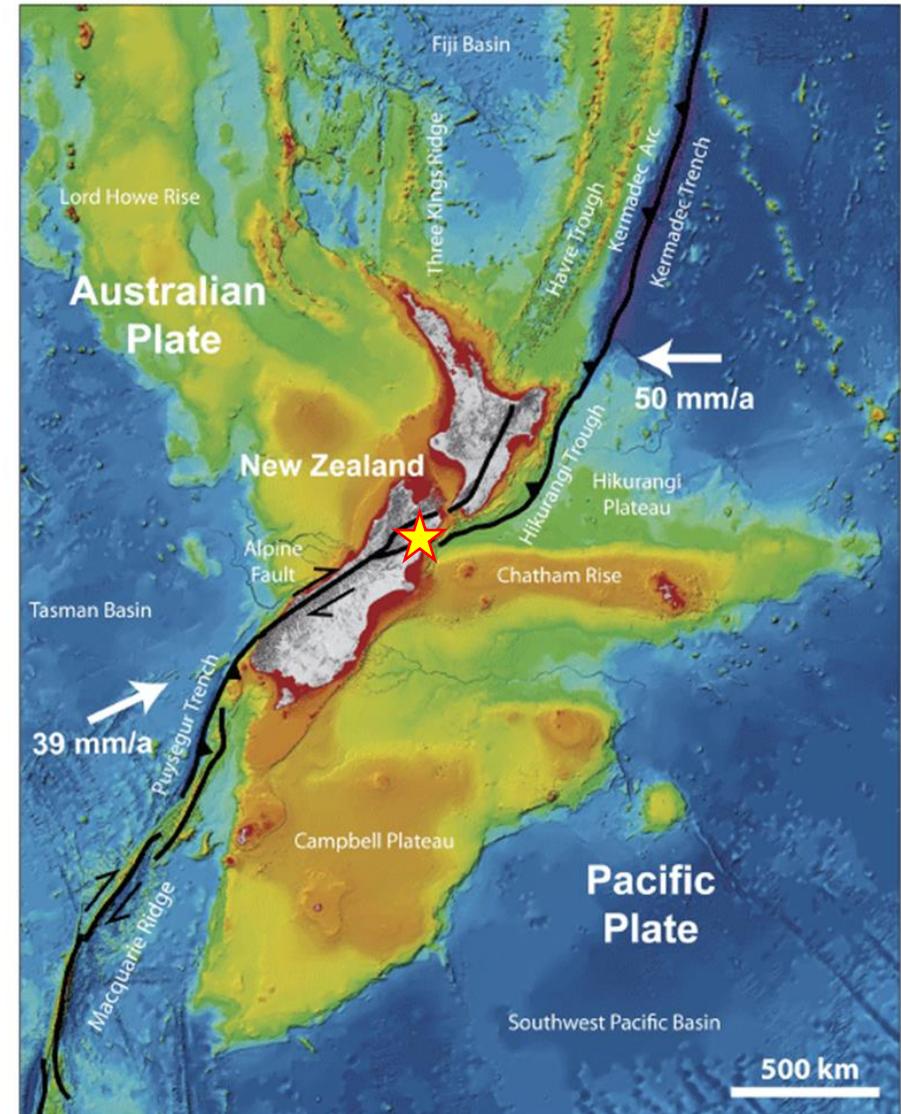
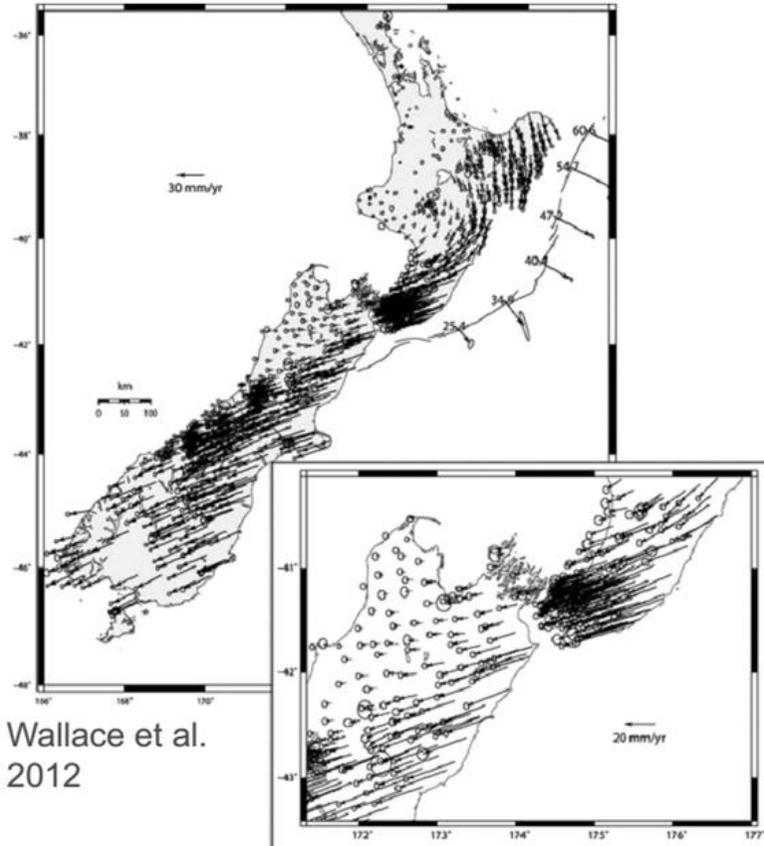
Blenheim 31,000  
 Seddon 500  
 Kaikoura 2,100  
 Christchurch 390,000

100 km

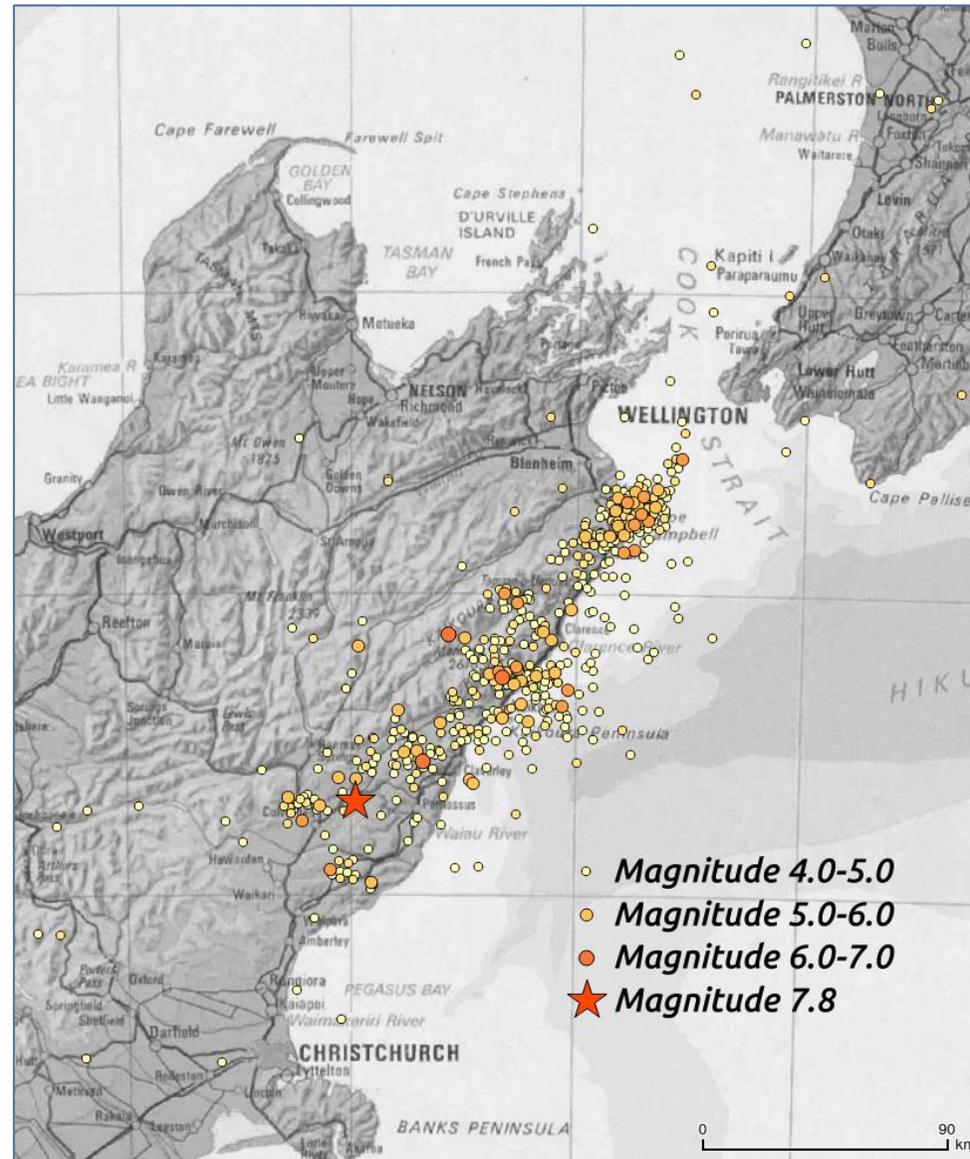


# Tectonic setting

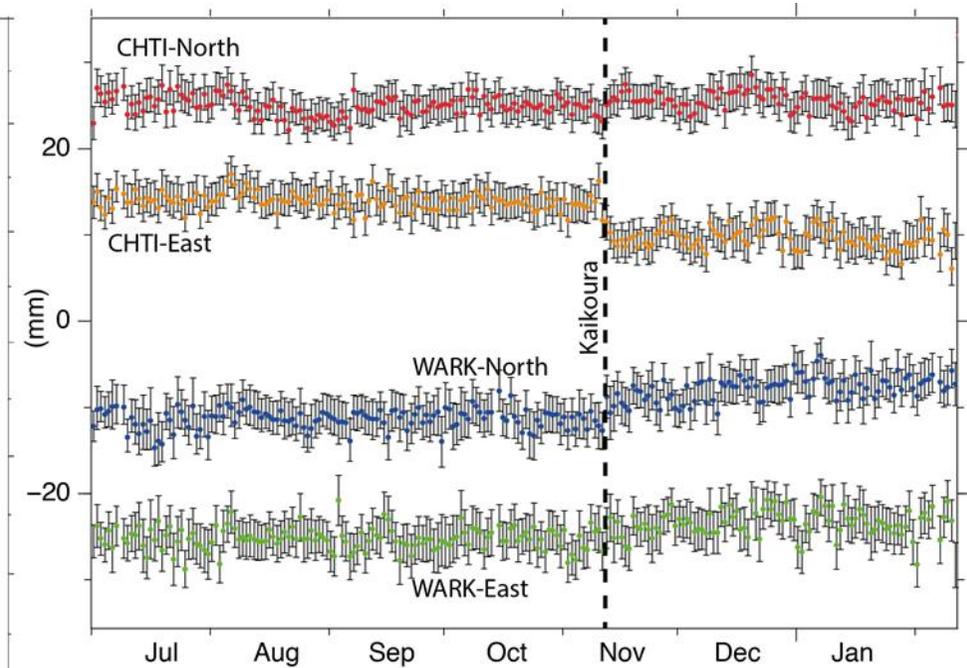
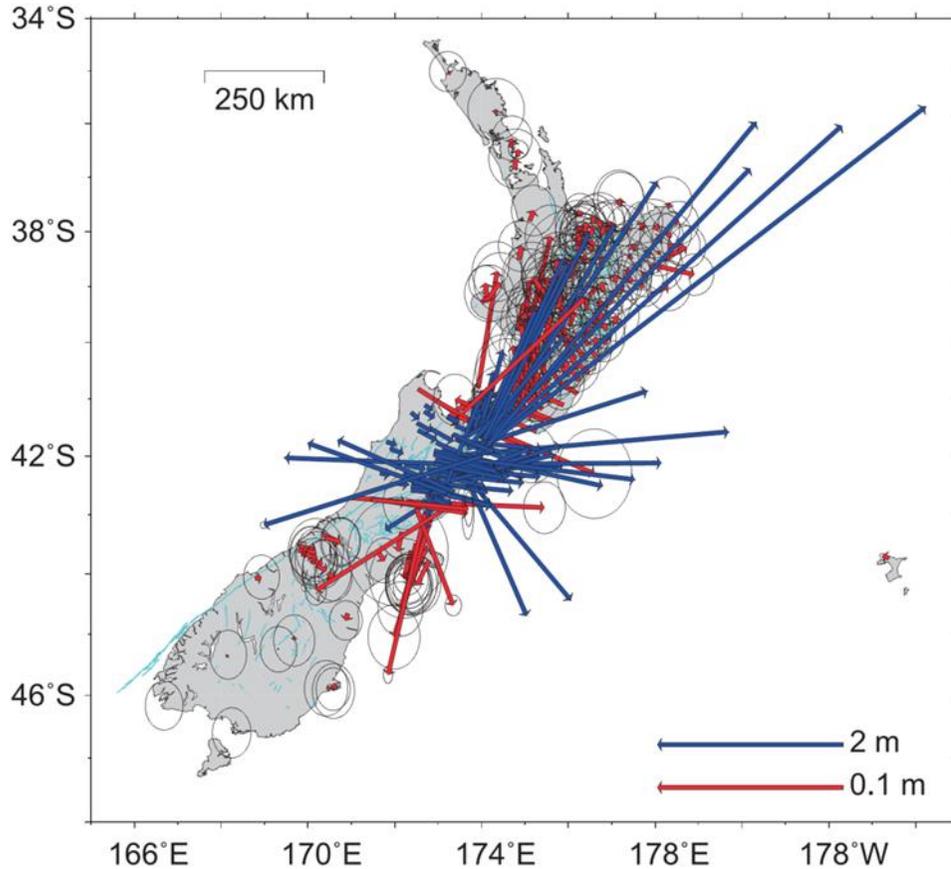
New Zealand tectonics are dominated by the continued collision between the Pacific and Australian plates.



# Seismicity

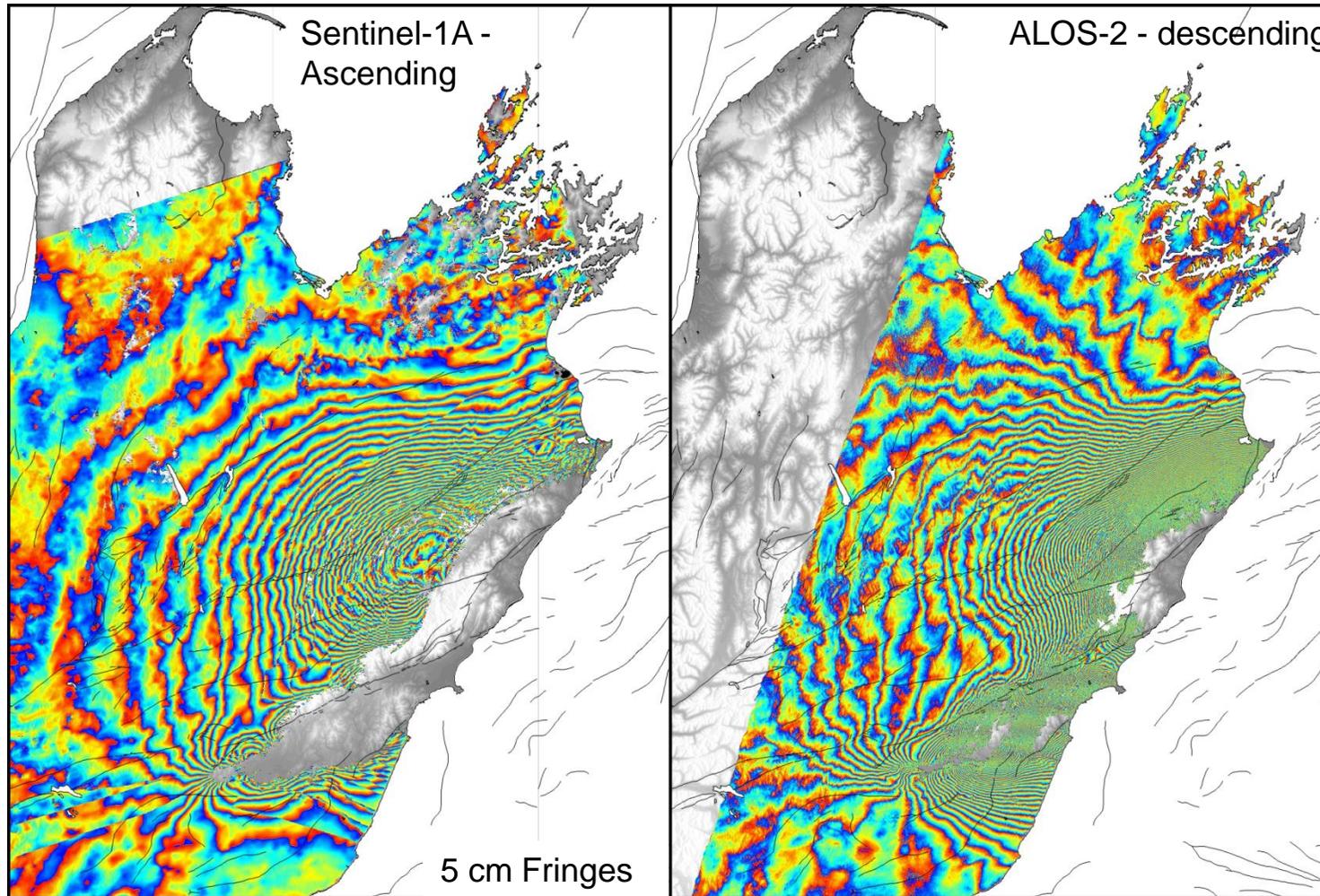


# Observations - CORS



Courtesy Ian Hamling – GNS Science

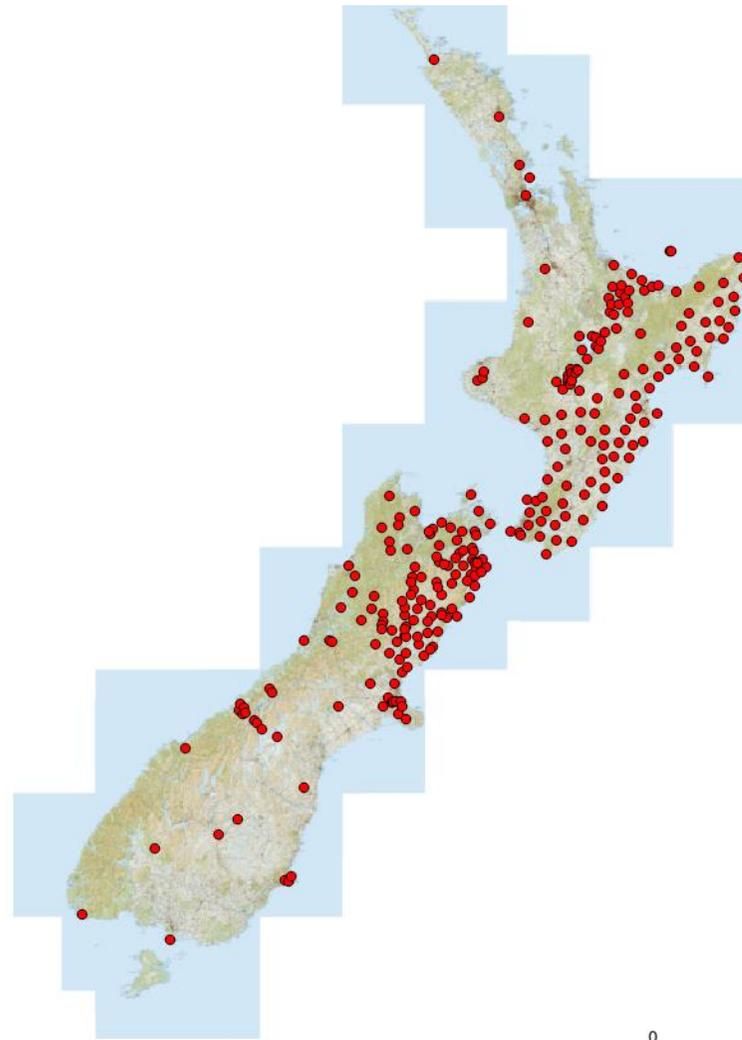
# Observations- InSAR



03/11/16 – 15/11/2016

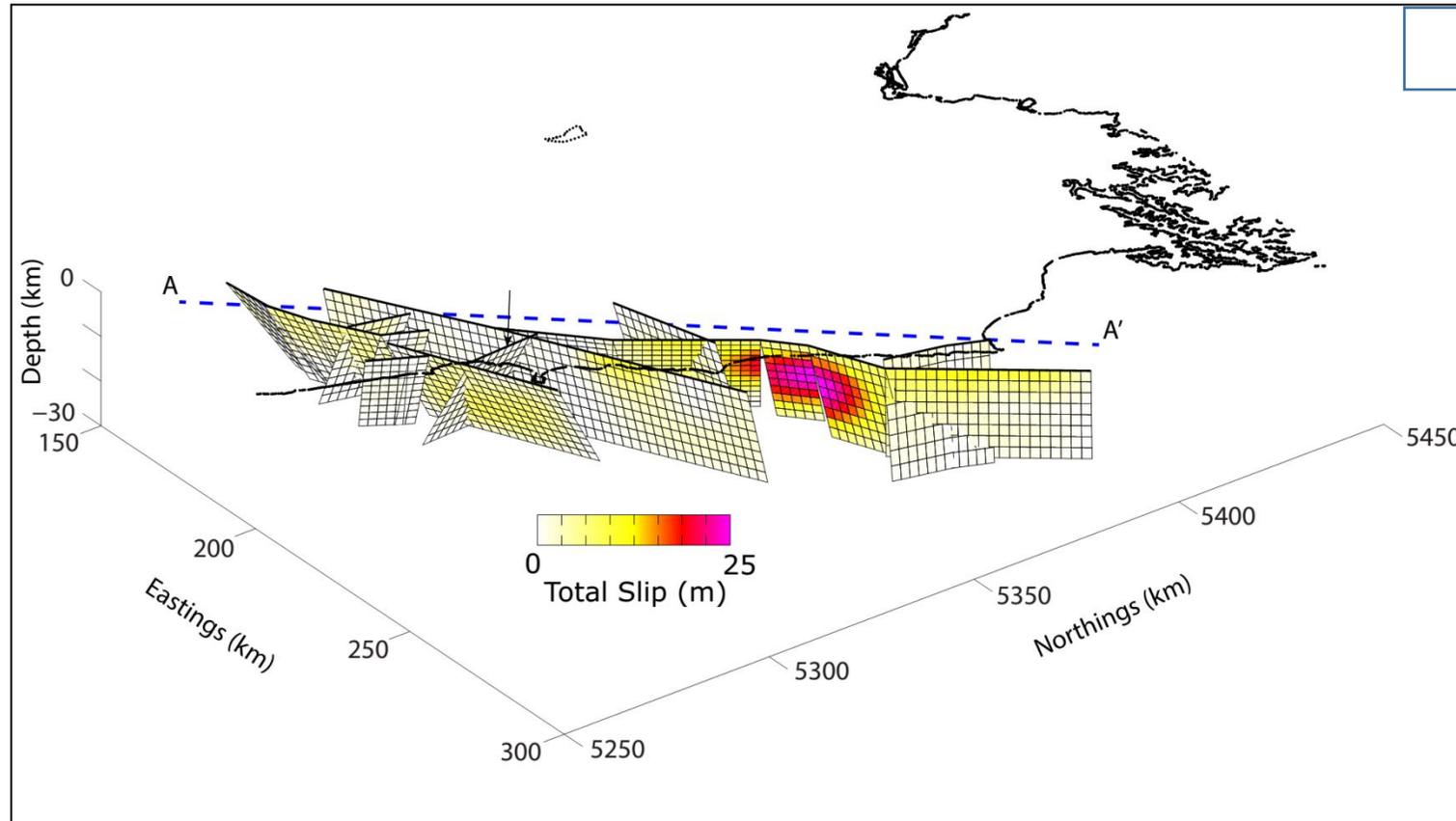
18/10/16 – 16/11/2016

# Observations- GNSS campaigns



0 400 km

# Geophysical model

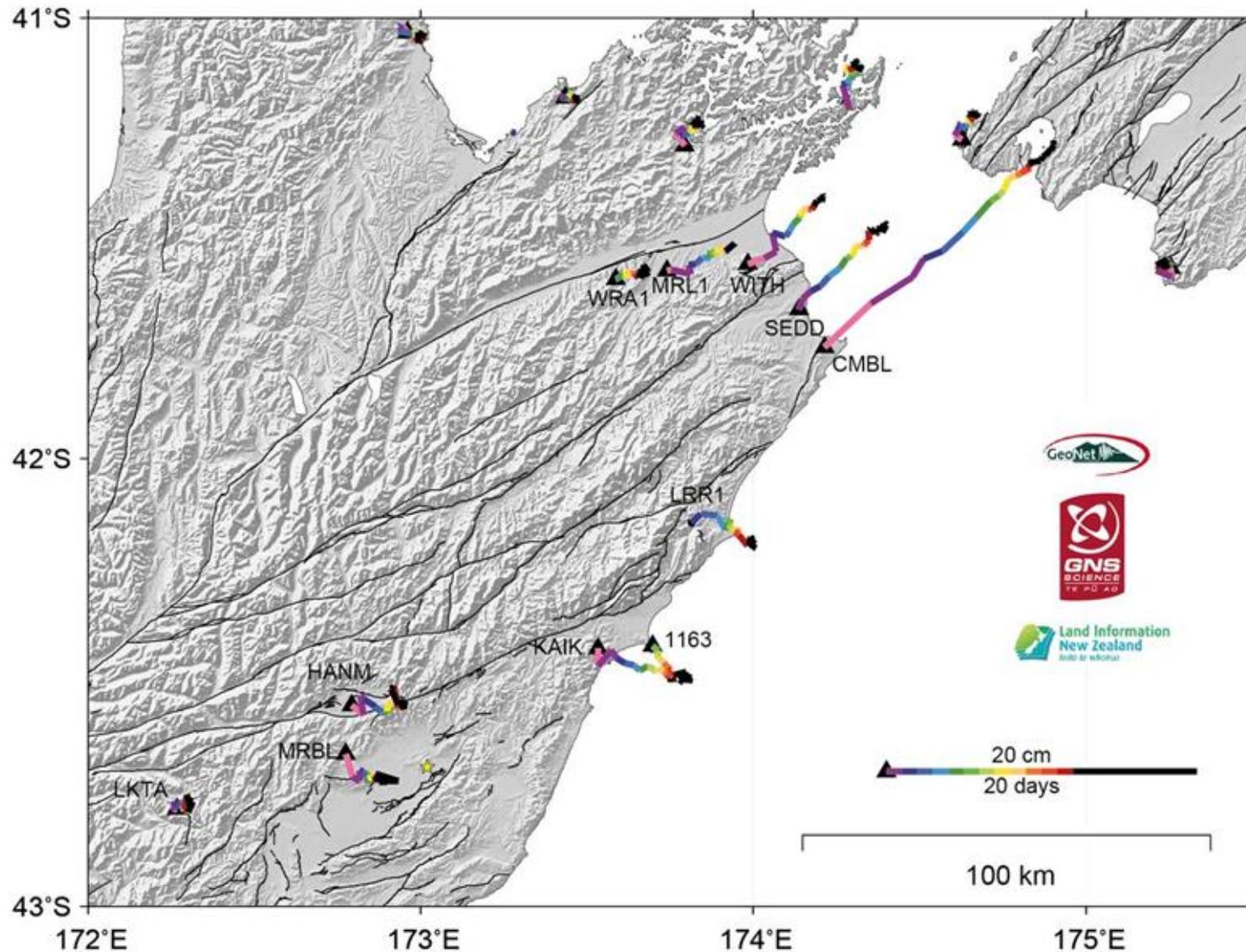


Calculated using Okada (1985) formulae for surface displacement caused by slip on a rectangular fault.

Initial model based on seismology and geology

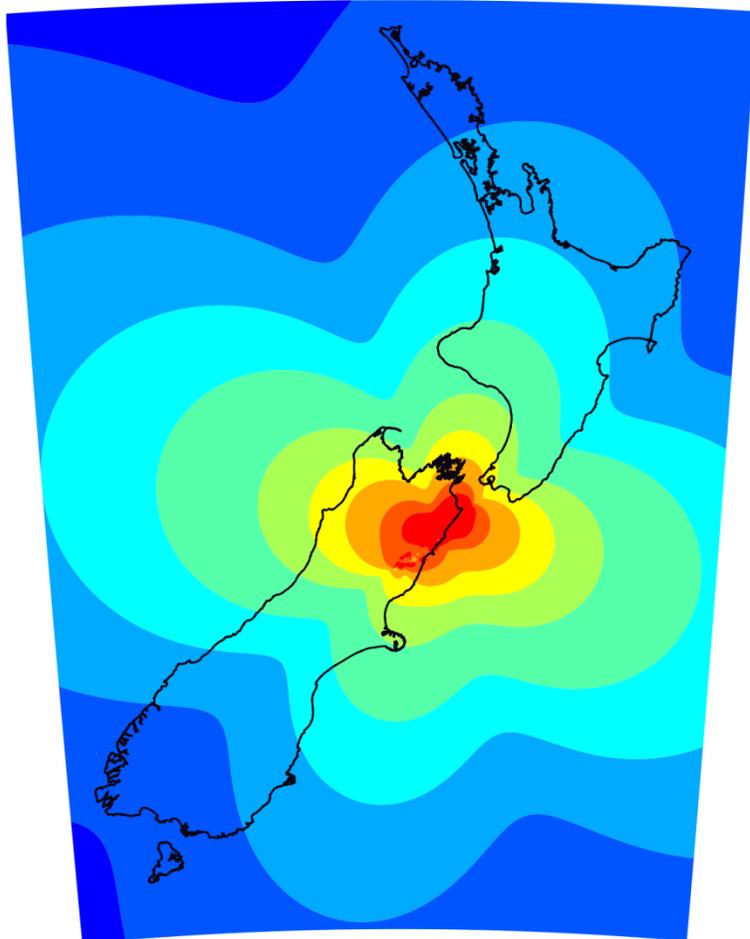
Inverted to fit GNSS, InSAR, and LiDAR data.

# Post-seismic deformation

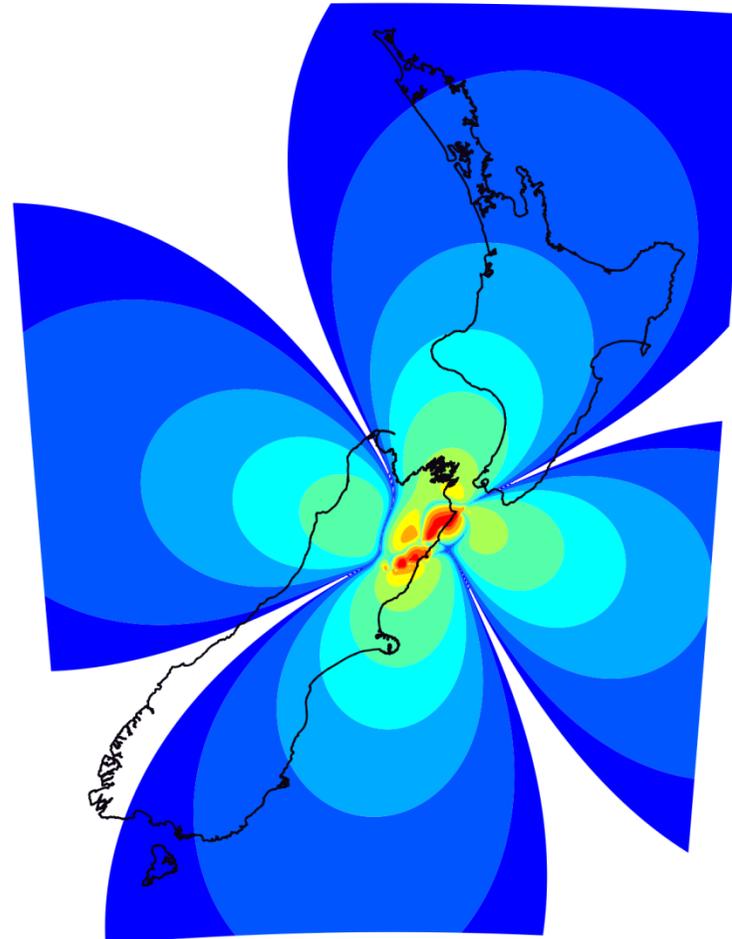


# Derived surface displacements

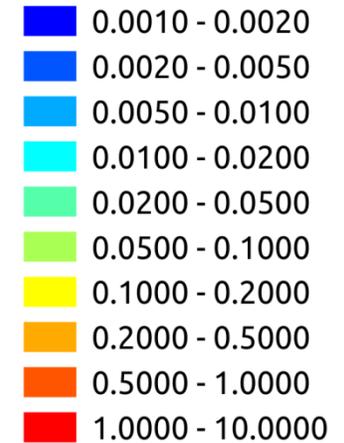
## Horizontal movement



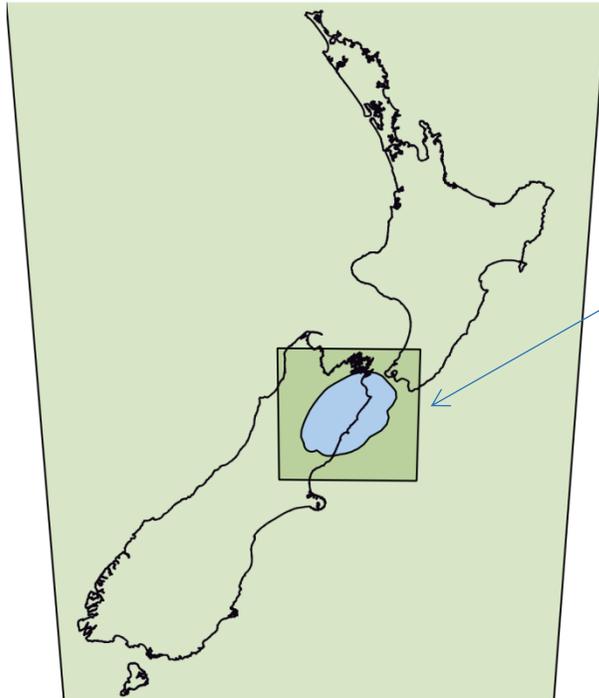
## Vertical movement



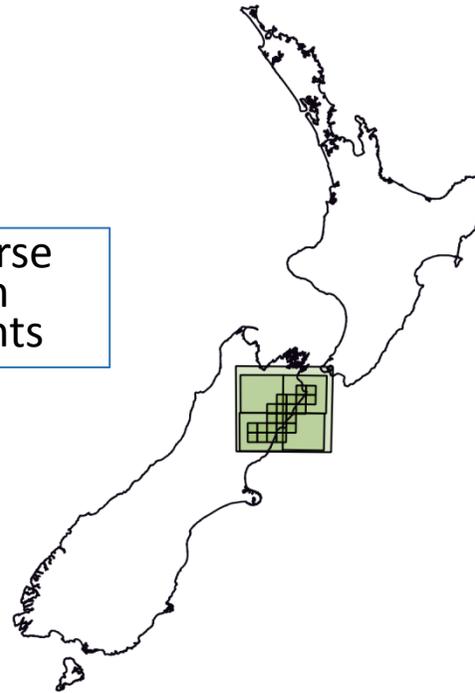
### Magnitude of movement



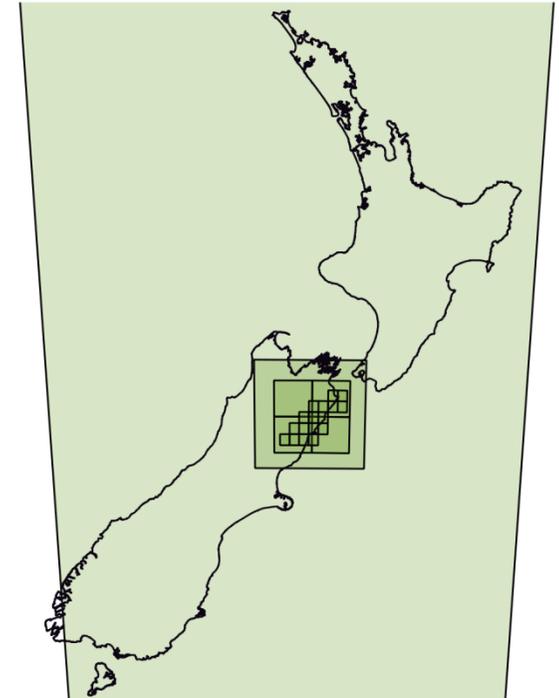
*Forward horizontal patch*



*Reverse horizontal patch*



*Reverse vertical patch*



Reverse  
patch  
extents

Forward patch – changes deformation model but not coordinates

Reverse patch – changes coordinates and deformation model

Approximate grid spacing

Level 1: 13.4 km

Level 2: 3.4 km

Level 3: 840 m

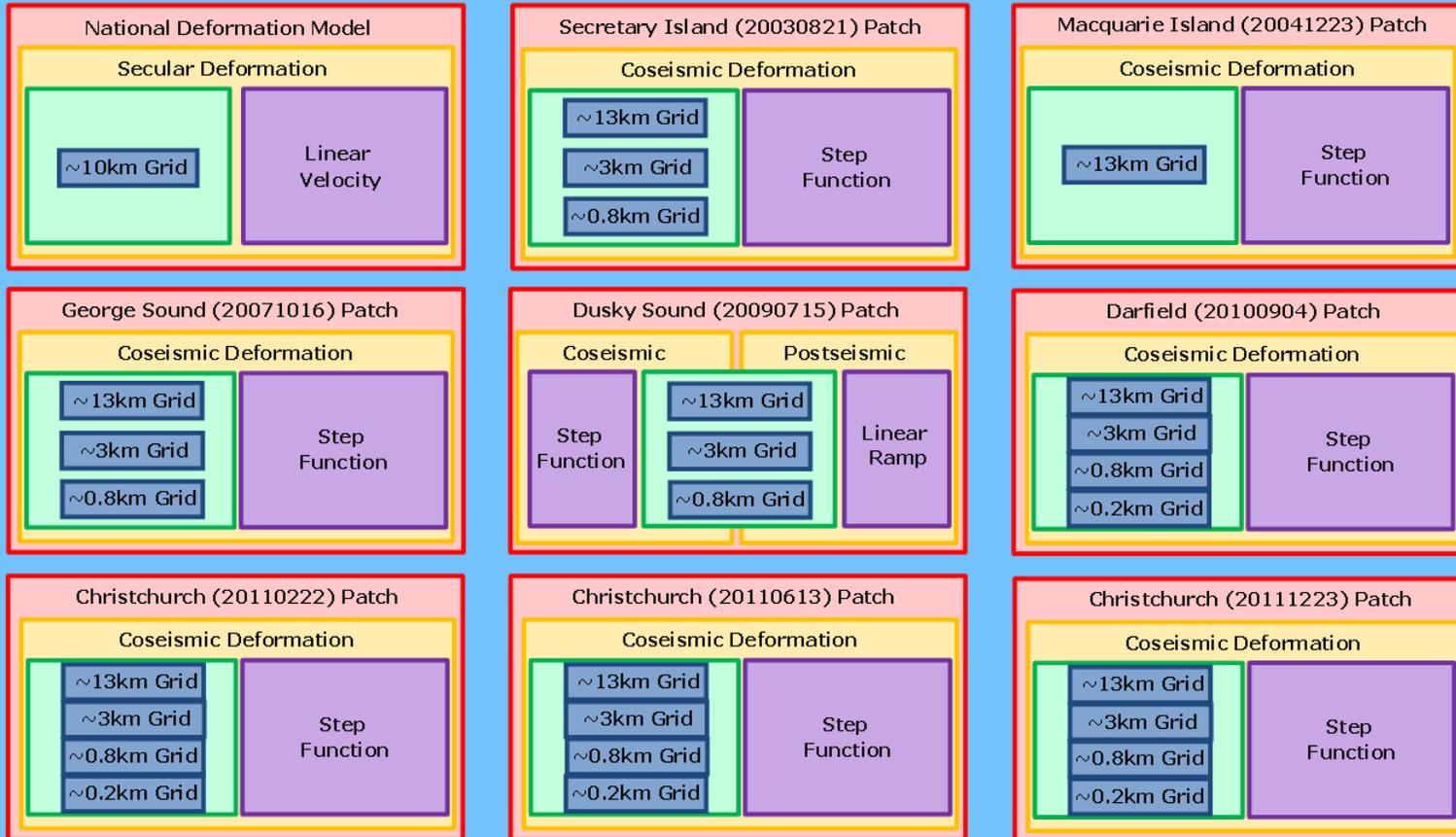
Level 4: 210 m

Published in a number of formats

- Official model definition as CSV (comma separated value) files published on the LINZ website\*\*
- NTV2 files for the horizontal reverse patch grids to facilitate updating GIS databases
- Incorporated into LINZ coordinate conversion products – online conversion and downloadable software (eg SNAP survey network adjustment software)
- Implemented into LINZ processes such as NZGD2000 coordinates calculated in PositionZ-PP online GNSS post processing service
- Reverse patch coordinate updates applied to published LINZ data sets where appropriate (eg cadastral parcel data)

*\*\* Not currently supported by 3<sup>rd</sup> party software*

## NZGD2000 DEFORMATION MODEL v20130801



# Supporting post-eq surveys



# Online support



Online support covering:

- Post-earthquake control survey methodologies
- How to reference coordinates
- Land movement maps

Provide direct support for survey profession in analysing survey data and providing “authoritative” reference coordinates.

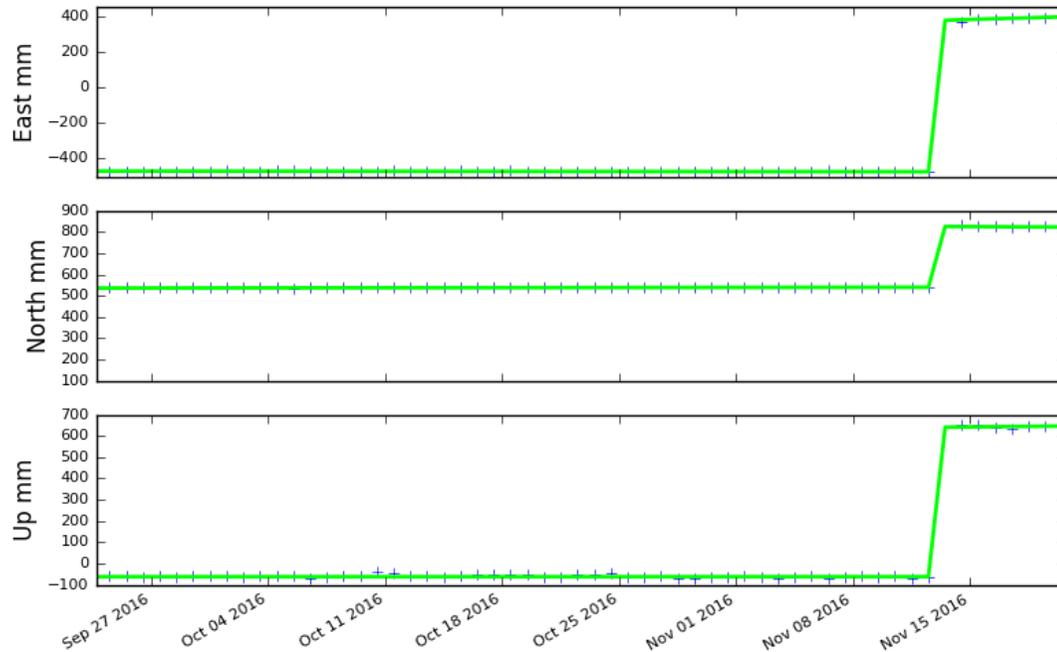
East and north accuracy (95% confidence level) (m)		Height accuracy (95% confidence level) (m)		Minimum distance between control marks (m)	Minimum time for each occupation (2 occupations for each mark required) (hours)	Order	
Local (vector between control marks)	Network (coordinate in terms of PositionZ stations)	Local (height change between control marks)	Network (height in terms of PositionZ stations)			NZGD2000	NZVD2016
0.010	0.005	0.015	0.010	4000	16	3	1V
0.010	0.005	0.015	0.010	1500	16	4	2V
0.020	0.015	0.030	0.020	3000	4	4	2V
0.020	0.015	0.030	0.020	300	4	5	3V
0.030	0.020	0.050	0.040	700	3	5	3V
0.040	0.030	0.060	0.050	1500	2	5	3V

# PositionNZ-PP update

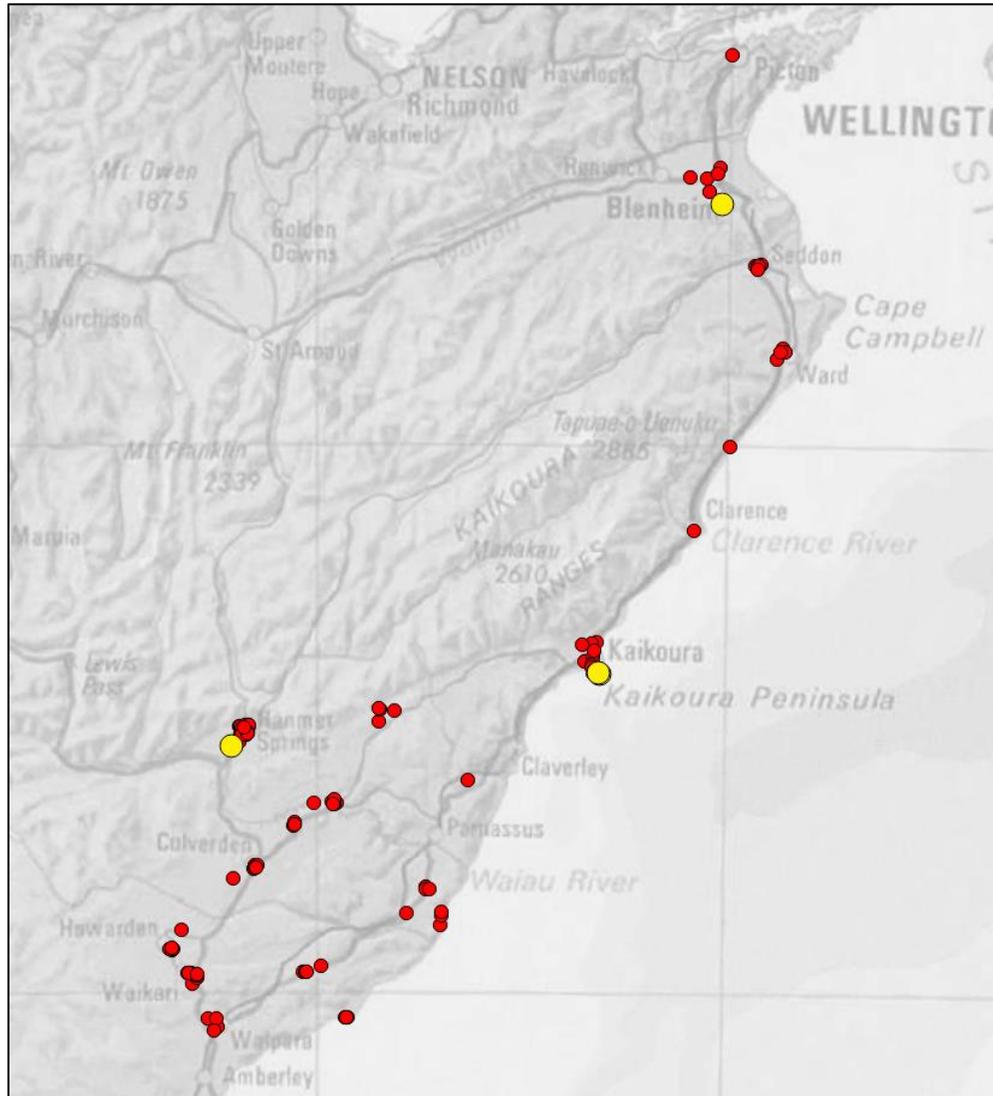
## PositionNZ-PP online GNSS post processing service

- Update station coordinate models defining reference coordinates of stations.
- Allows surveyors to generate new control marks

KAIK time series



# Post earthquake urban control

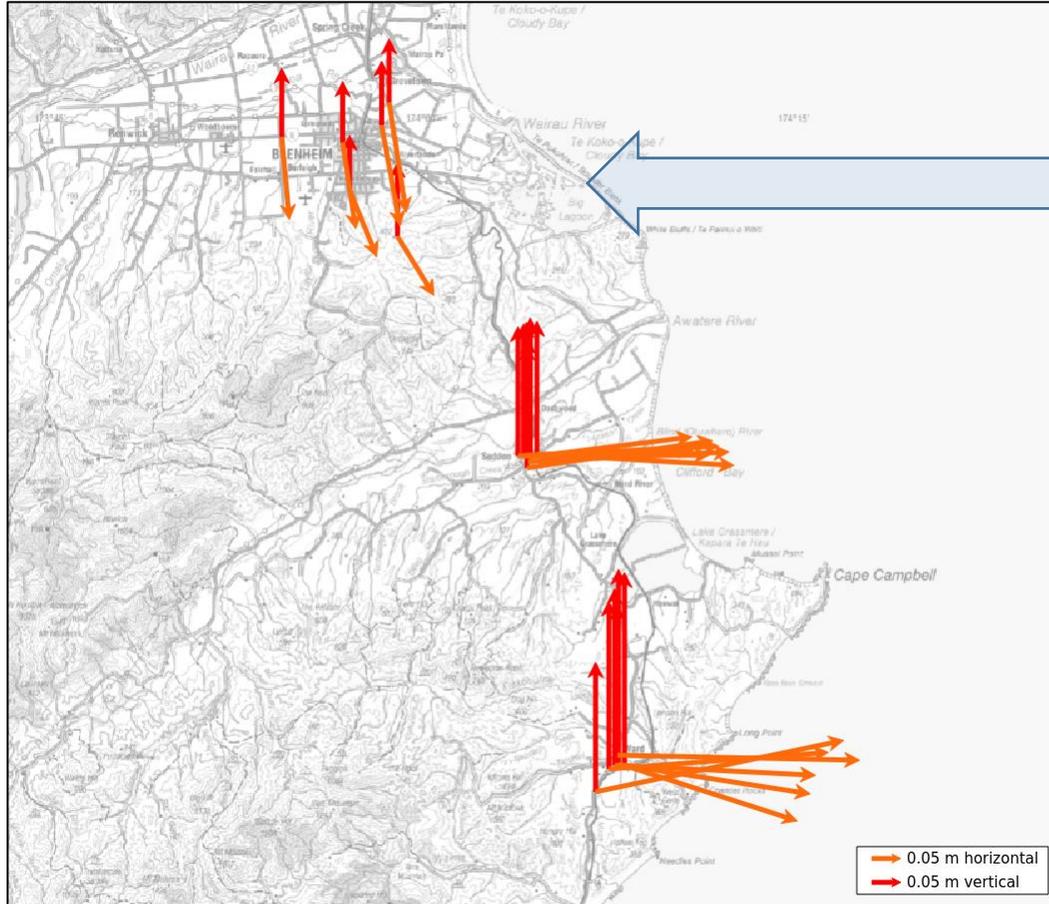


Urban control surveyed within 1 month of earthquake

4-hour plus 1-hour GNSS occupations at base station in each locality (yellow)

Other marks surveyed with RTK

# Post earthquake urban control

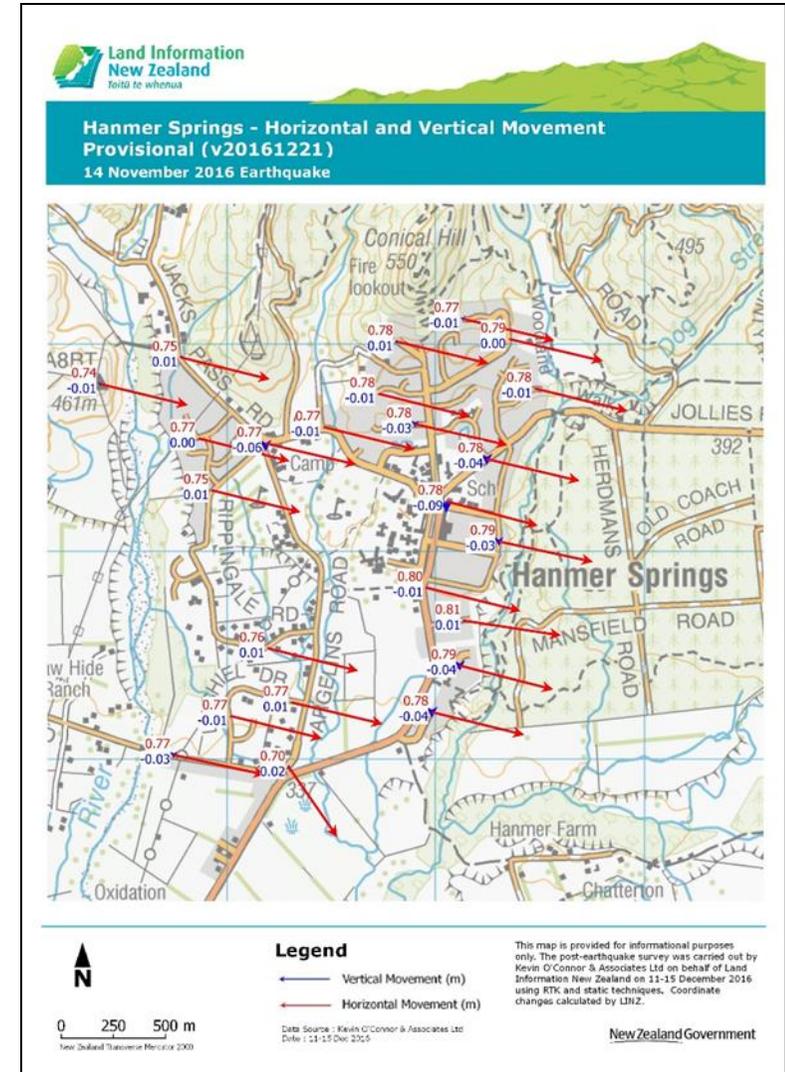


Code	dE	dN	dH
ACYP	0.175	0.586	0.027
APKE	0.187	0.626	0.033
BEOG	0.173	0.563	0.046
APCA	0.185	0.633	0.033
B8RP	0.235	0.744	0.037
WITH	0.285	0.898	0.092

# Post earthquake urban control

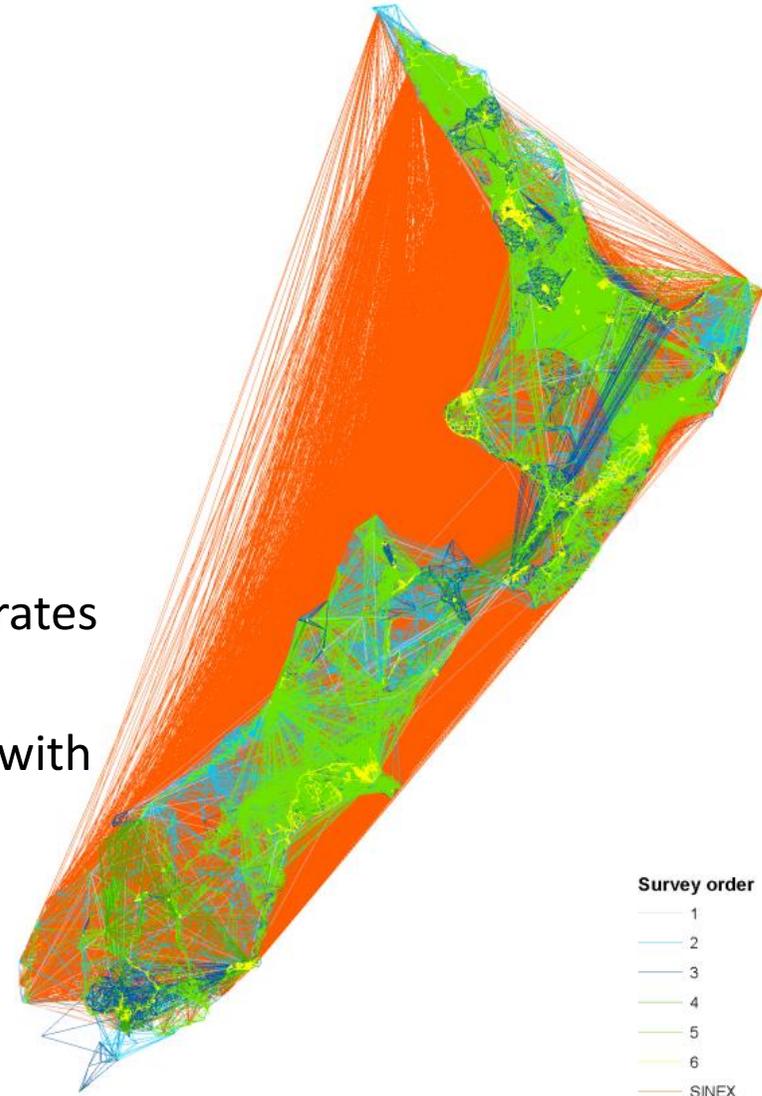
New control coordinates published using online “LINZ data service (<http://data.linz.govt.nz>)

Also published as PDF maps for each town.



# National Geodetic Adjustment

- > 100,000 marks
- Includes:
  - All GPS/GNSS data since 1990s
  - Terrestrial geodetic observations
  - Levelling observations
- Using LINZ SNAP software which incorporates deformation model into adjustment
- Entire network updated to be consistent with new deformation model





# Question?