


FIG Working Week 2004
 Athens, 4-7 October 2004

**Large Scale Metrology
 for Research and Industry**
**Application to Particle Accelerators
 and Recent Developments**

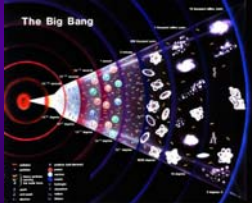
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 CERN, 1211 Geneva 23

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What is CERN? Why HEP research?

- European Organisation of 20 member-states + associates
- World's largest Laboratory for Particle Physics (9000 persons)
- Fundamental research in High Energy Physics


The Big Bang




The forces in Nature


Force	Relative Strength	Range	Carrier Particle	Notes
Gravitational	$\sim 10^{-39}$	Infinite	Graviton	Always attractive
Electromagnetic	$\sim 10^{-2}$	Infinite	Photon	Attractive & repulsive
Weak Nuclear Force	$\sim 10^{-13}$	$\sim 10^{-16}$ m	W/Z bosons	Always attractive
Strong Nuclear Force	$\sim 10^{-8}$	$\sim 10^{-15}$ m	Gluons	Attractive & repulsive

(The diagram also shows a balance scale comparing the forces.)

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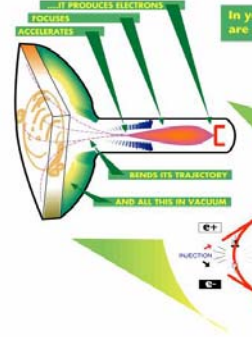

Why surveyors at CERN ?

- ◆ 65 km of beam lines, >8500 elements "aligned" and surveyed
- ◆ High precision requirements on accelerators : 0.1 mm to a few μm
- ◆ Huge detectors on experimental areas and caverns, also capable of tracking particles within 0.1 mm to a few μm
- ◆ Ambitious projects and unusual challenges : focussing particle beams to a few nanometres and colliding them, or sending particles towards a detector at 732 km...

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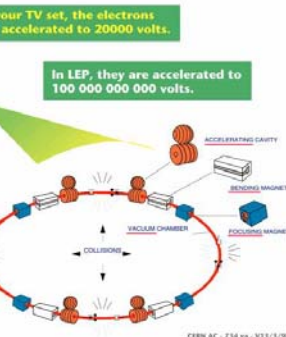
DID YOU KNOW YOUR TELEVISION SET IS AN ACCELERATOR ?


IT PRODUCES ELECTRONS
FOCUSES
ACCELERATES
BENDS ITS TRAJECTORY
AND ALL THIS IN VACUUM



In your TV set, the electrons are accelerated to 20000 volts.

In LEP, they are accelerated to 100 000 000 000 volts.




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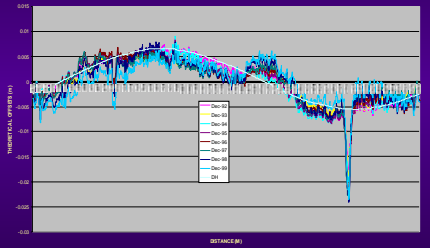






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Stability of LEP (27 km) : annual levelling before realignments

THE RESTORED MEASUREMENTS WITH RESPECT TO LEVELLING DEC92



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Comparing successive surveys

Successive surveys of a perfectly rigid and stable object :
if random errors only, all "wrong" lines have the same likelihood to be true...

Stable traverse of arc AB of length L_m

No deformation signal there, only measurement noise (random errors):
Beware of biased conclusions...

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Horizontal Surveys : combined effects

- The overall changes of curvature are induced by errors (random & systematic) in distances and/or in radial measurements, but also by those of control points;
- The general pattern - i.e. the polynomial order of the trend curve - depends on the scheme and quality of the measurements (redundancy, accuracy, overlaps);
- Local dispersion (smoothness) depends on resulting short range errors;

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Comparing surveys : what is it looked for ?

Seeing & correcting true deformations :
"ad hoc" local comparisons

Restoring a functional alignment and
correcting singular movements :
smoothing process

Assessing the alignment decay :
statistics on alignment changes

$\sigma_{n+1} \neq \sigma_l$

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The smoothing concept

- The initial alignment consists in reducing the scattering to within the specification (0.10 to 0.15mm r.m.s) by moving selectively the misaligned components
- Maintenance alignments aim to restore this situation at the optimum of functional values whenever needed
- Smoothing algorithms can be parametric or non parametric, and data processing is made in a sliding window - with an adjustable threshold which optimally selects, from local fits and statistics, the components to move back to a better position.

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Past developments made at CERN for managing 0.1 mm accuracy

<p>Distinvair</p>	<p>Wire Offset measuring device</p>
<p>In situ Interferometry with self-aligning reflector</p>	<p>Force-centring reference socket</p>

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New developments for managing a few μm accuracy

<p>Wire Positioning System (WPS)</p> <p>One or two axes Measurement range : $\pm 5\text{mm}$ Resolution: $0.1\ \mu\text{m}$; Repeatability: $1\ \mu\text{m}$ Bandwidth: 0-10 Hz</p>	<p>Hydrostatic Levelling System (HLS)</p> <p>Measurement range : 5 mm Resolution: $0.2\ \mu\text{m}$; Repeatability: $1\ \mu\text{m}$ Bandwidth: 0-10 Hz</p>
<p>Tilt Meter System (TMS)</p> <p>Biaxial measurement of tilt and acceleration Measurement range : $\pm 10^{-2}$ radian Resolution: 10^{-7} radian ; Repeatability : 10^{-6} radian Bandwidth: 0 to 100 Hz</p>	<p>Actuators</p> <p>Stepwise motorization Length at mid course : 155mm Diameter : 60mm ; Travel : $\pm 4\text{mm}$ Resolution : $0.2\ \mu\text{m}$; Repeatability : $1\ \mu\text{m}$ Maximum load along the trust axis : 400 N</p>

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HLS system in ΔH and Δt areas (Δp managed)

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Precisely linking both sides of LHC low β - areas

Invar rods + sensors
 Stretched wire
 Wire Positioning System (WPS)

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Monitoring and maintaining an active alignment to within $3 \mu\text{m}$ on CTF

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Alignment of future linear colliders over $2 \times 15 \text{ km}$ beam lines

quadrupôle poutre de fil ligne optique réseau hydrostatique point d'articulation des poutres plaque de référence
 Capteur à fil tendeur de fil réseau hydrostatique capteur optique oscillomètre

Mesures
 stricte détermination surabondance

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Accurately checking the alignment of rails

"METROLOGICAL TRAIN" CONCEPT

slippers
 Main Rail
 distance sensor
 pulley
 winding motor
 bi-axial inclinometer
 swivel
 rigid link between swivels
 winding drum
 offset measurement
 rail
 slipper

Additional wagon: for electronics, power supply, DAC, cable interfaces

Approximate scale: 10 cm

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CERN Calibration Facility : The 50 m length and offset benches

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Main features of the calibration benches

- ◆ Calibration of lengths (interferometric bench) :
 - ◆ Reference : interferometer ($\sigma < 0.1 \mu\text{m}$)
 - ◆ Carriage : manual or automatic mode
 - ◆ Calibrated instruments : invar wires, electro-optical distance-meters (for constant & cyclic errors), passive or active linear gauges, engraved tapes, scale bars, levelling staves
- ◆ Calibration of alignment systems (bi-axial offset bench) :
 - ◆ High precision capacitive sensors and inclinometers
 - ◆ Vertical reference line : hydrostatic levelling ($\sigma = 2 \mu\text{m}$)
 - ◆ horizontal reference : stretched wire ($\sigma = 5 \mu\text{m}$)
 - ◆ Carriage : manual, with all position parameters measured
 - ◆ Calibrated instruments and systems : wire or laser offset measuring devices, telescope & target alignment systems, optical polar systems (theodolites/total stations, laser trackers or scanners)

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Layout of the bi-axial offset calibration bench

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From large scale metrology to large scale geodesy : sending neutrino beams far away

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The CNGS geodetic problem

$$dN = [H_{\text{HLS}} - H_{\text{W}}] - [h_{\text{HLS}} - h_{\text{W}}] = [H_{\text{HLS}} - H_{\text{W}}] - [h_{\text{HLS}} - h_{\text{W}}] + e$$

$\sigma_{(H_{\text{HLS}})} \approx 1.4 \text{ à } 2 \text{ mm}$
 $\sigma_{(h_{\text{W}})} \approx 0.6 \text{ mm}$

Objectif : 30 m à 732 km : 4×10^{-5}

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CONCLUSIONS

- ◆ Research has always been the most demanding for all applied sciences and technologies, in all professions
- ◆ Surveying for research works => research works for surveying
- ◆ It has to remain a surveyor's concern => multidisciplinary approach, collaboration with universities and industry

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