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Volunteering for the future – Geospatial excellence for a better living

# Set provert for dynamic datums in Trimble software

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Coordinates transformed to common reference epoch 2000 for New Zealand using deformation model cGNSS for active control

#### Deformation models

correct for tectonic motion between the epoch of measurement and the National datum Reference epoch



**Euler Poles** 

Average Velocity only Velocity + EQ +PS Distortion grid: Displacement between t and reference epoch

#### NAD83 (2011) CONUS



- HTDP3.4 has 3 new earthquake models
  - Ridgecrest earthquake in California and 2 in Alaska
  - Ridgecrest earthquake caused surface rupture so we used 2 nested grids with a high resolution patch near the epicenter



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### Implementation in Trimble Software



Our generic time dependent transformer can convert:  $(X, Y, Z)_{ITRF}$  at eom from or to  $(X, Y, Z)_{IOCAL}$  at eor



- It uses **data files** modeling: Datum transformation (14 p transformation or grid) Displacement models (with secular velocity & earthquake patches)



Models addition & updates are easy deploying new data files.

## Map of displacement models



**Euler Poles Velocity grid** Velocity + EQ +PS **Distortion grid: Displacement** between t and reference epoch



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### Conclusions

- TGL has been upgraded to support time dependent datum transformations
- Includes a grid based algorithm to support deformation models
  - Based on the approach used by Land Information New Zealand
  - It can be used to support any national deformation model
- It is consistent with the OSG's proposed standard for deformation models
- Future deformation models should follow OGC standard for easy and consistent deployment across software vendors



