

## **Voxel modelling for large 3D urban areas**

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#### Advancing Spatial Digital Twins with Voxel-Based 3D Data Processi

- Spatial Digital Twins are key platforms for managing and visualizing 3D spatial data.
- Data is organized into themes (terrain, transport, vegetation) or ad hoc datasets (buildings).
- Integrating 3D data into a unified model presents challenges in accuracy, resolution, and representation.

## UOXELMATES.coma

- Voxelmates consists of four mates from TUDelft/UNSW and one developer
- Voxelmates is a member of the ESRI Partner Network



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#### **Challenges in Current Spatial Digital Twins**

- Much urban data is structured as raster or vector datasets
- Difficulties arise when combining these data, hence;
- Lack of advanced 3D spatial analysis (e.g., volume computation, 3D intersections).

AND Locate25

Voxel-based representation offers a unified and efficient solution.

Buildings	Terrain	Transportation (rail, roads, etc.)	Water	IoT Sensors
3D Polygons	DEM (grid)	3D Lines and 2D Polygons	3D Lines and 2D Polygons	Values / feeds
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#### **Voxel-Based Representation**

- Voxels are the 3D equivalent of pixels in raster images: Volumetric (vox) Elements (els)
- Objects are represented as sets of voxels in a regular 3D grid
- Variable grid size, multiresolution
- Voxel advantages:
  - Unified data structure
  - Robust neighbourhood operations
  - Powerful 3D analytics for urban applications across full 3D space, including airspace.



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#### The Challenge of Large-Scale Voxelization

- Fine-resolution voxels provide high accuracy but significantly increase data size.
- Data grows cubically with resolution, making city-scale models difficult to process.
- Requires efficient data structures for storage and analysis.









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#### Solution – Optimized Octree Data Structure

- Octrees provide an efficient way to manage voxel data hierarchically.
- Quadratic growth vs cubic growth in data size.
- Supports multi-resolution object representation.
- Optimized octree structure implemented in SQLite.
- Voxelmates have developed ESRI Add-ins for:
  - Accessing voxel data
  - Performing 3D analyses
  - Exporting LAS and NetCDF files.





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## **3D Data Integration**

- Enabling many spatial operations
  - Boolean (union, difference, intersection, etc.)
  - Clustering / Segmentation
  - Neighbourhoods / Connected Components
  - Morphology
  - Distance Transforms
  - Etc.

A grid of 3000x4000x100m at a resolution of 20cm would require 150Gb of memory! We got it only 1.9 Gb



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## **Urban Applications**





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City of Melbourne: vegetation change detection

Aerometrex: processing of reality meshes



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#### **Urban Applications**



Pathfinding in Point clouds



Sections



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Volume and area







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#### **Urban Applications**





Indoor analysis (hazard distribution)







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#### Key takeaways and next steps

- Voxel-based methods provide a structured, scalable approach to 3D data integration.
- Octree optimization significantly reduces memory and processing overhead.
- ESRI Add-ins enable practical implementation in existing GIS workflows for urban planning, infrastructure, and environmental modeling.
- We are keen to collaborate in developing and assisting:
  - Emergency response (indoor and outdoor)
  - 3D data fusion for different purposes
  - Microclimate and wellbeing (indoor and outdoor)
  - Safety and security (indoor, outdoor, underground)



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# **THANK YOU!**

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